

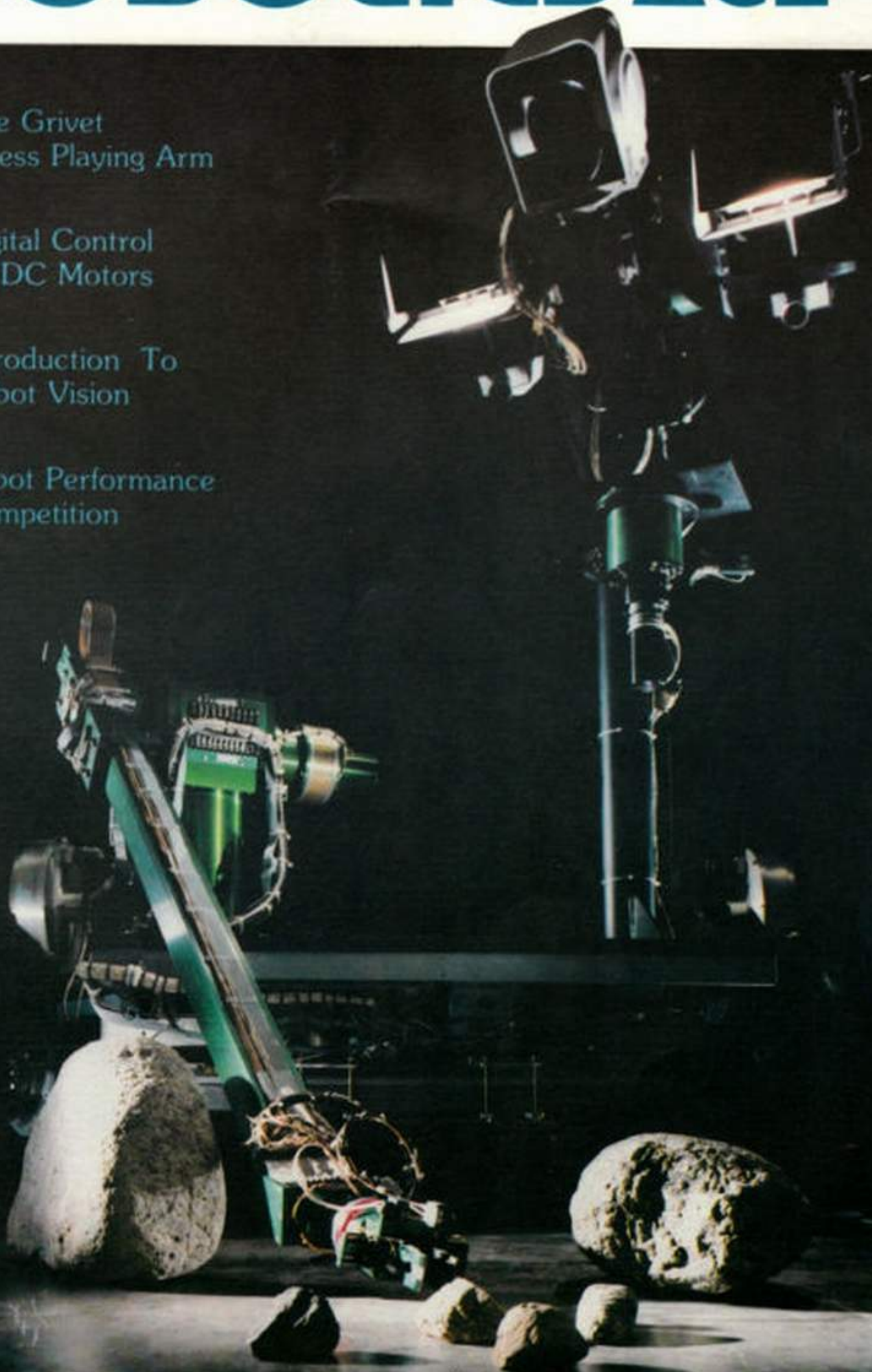
ROBOTICS AGE

The Grivet
Chess Playing Arm

Digital Control
Of DC Motors

Introduction To
Robot Vision

Robot Performance
Competition

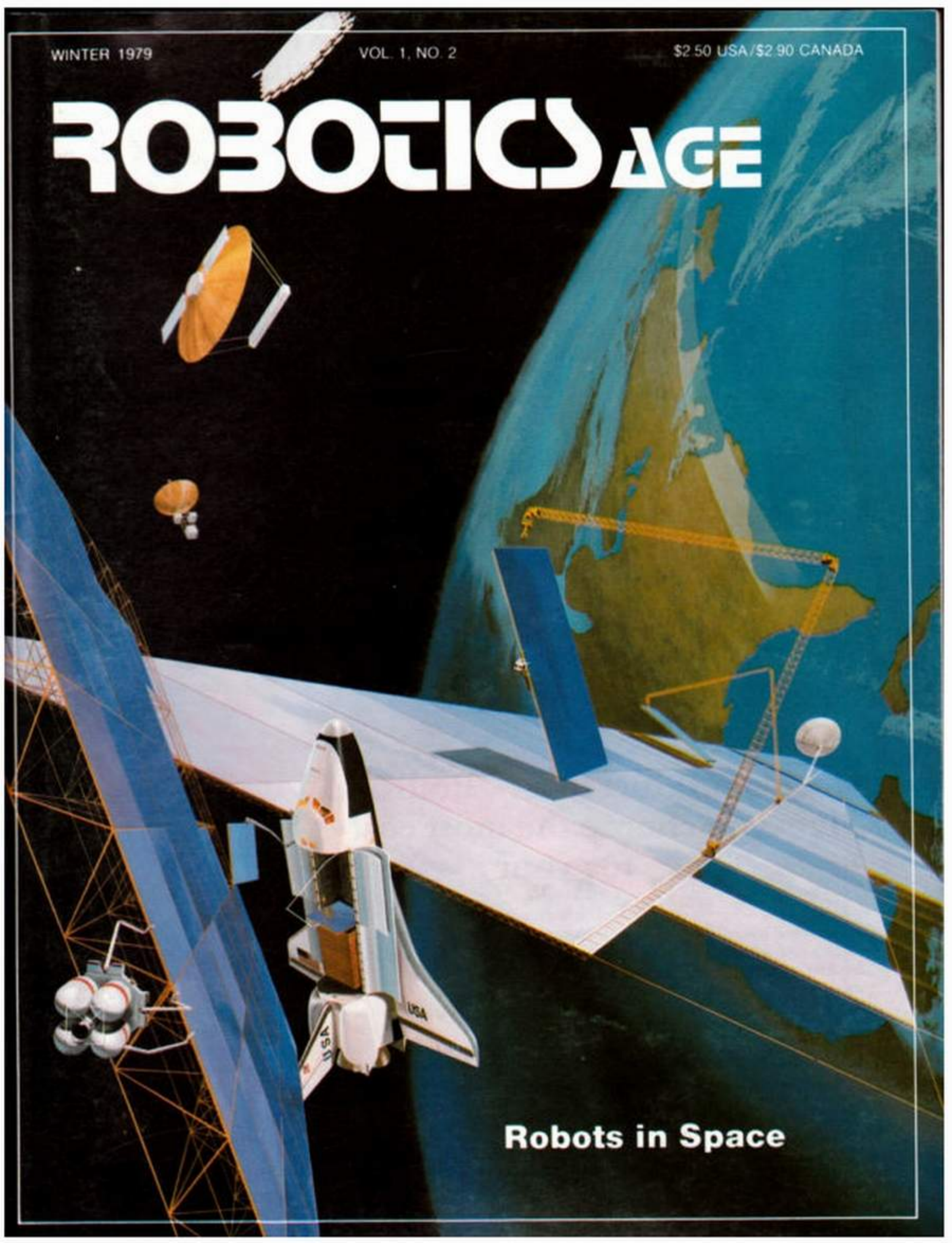


WINTER 1979

VOL. 1, NO. 2

\$2.50 USA/\$2.90 CANADA

ROBOTICS AGE



Robots in Space

SPRING 1980

VOL. 2, NO. 1

\$2.50 USA/\$2.90 CANADA

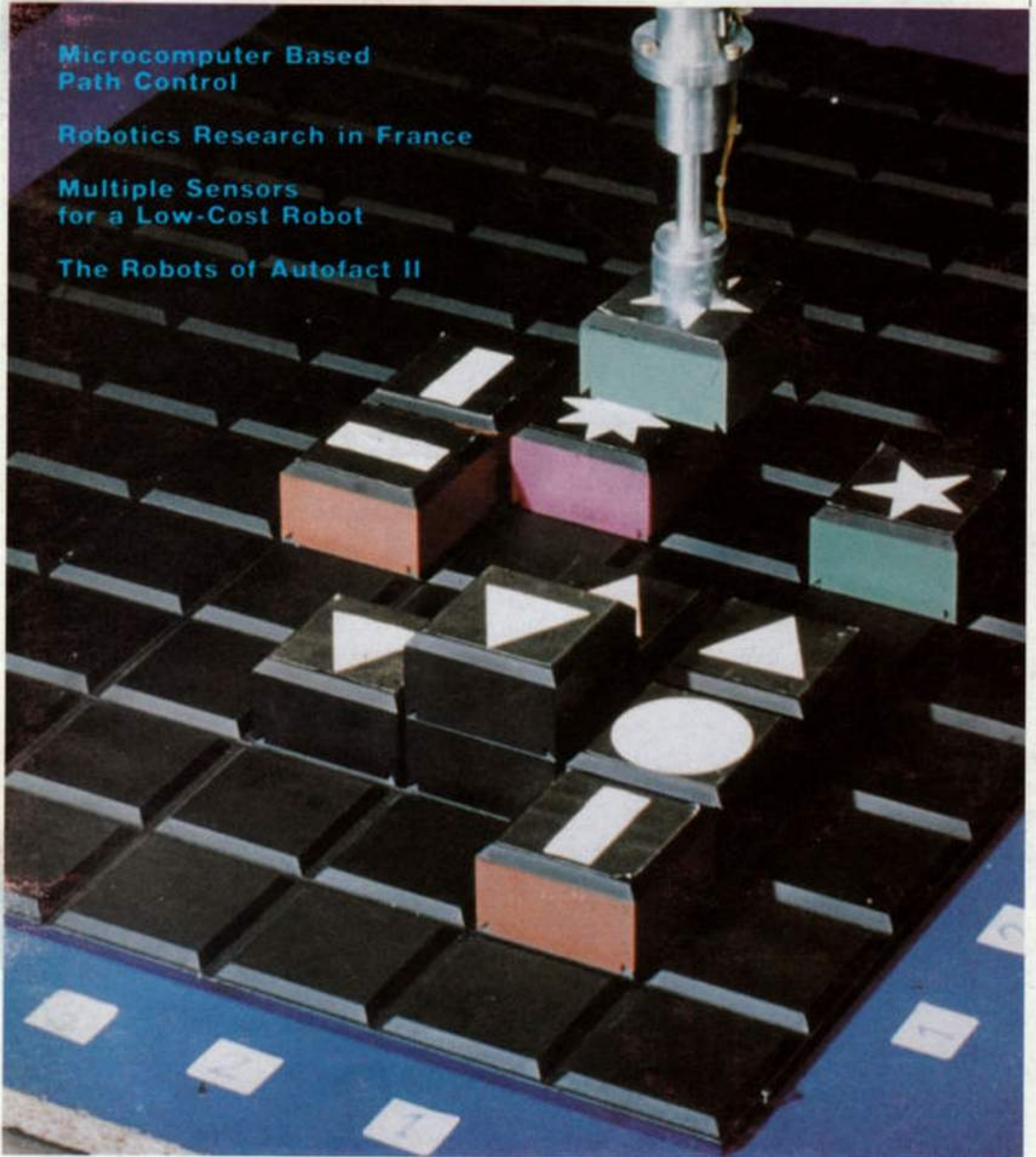
ROBOTICS AGE

Microcomputer Based
Path Control

Robotics Research in France

Multiple Sensors
for a Low-Cost Robot

The Robots of Autofact II

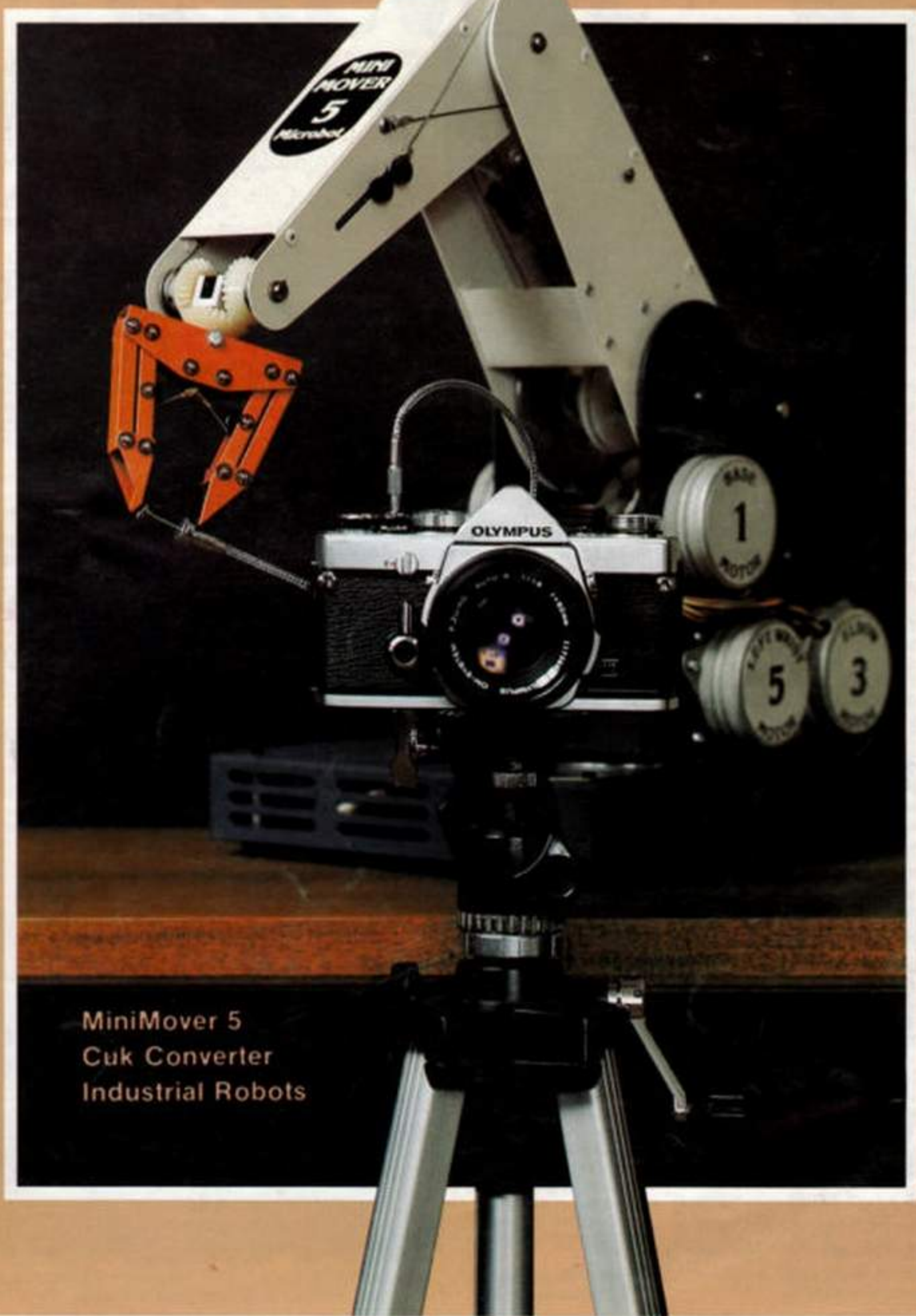


SUMMER 1980

Vol. 2, No. 2

\$2.50 USA / \$2.90 CANADA

ROBOTICS AGE



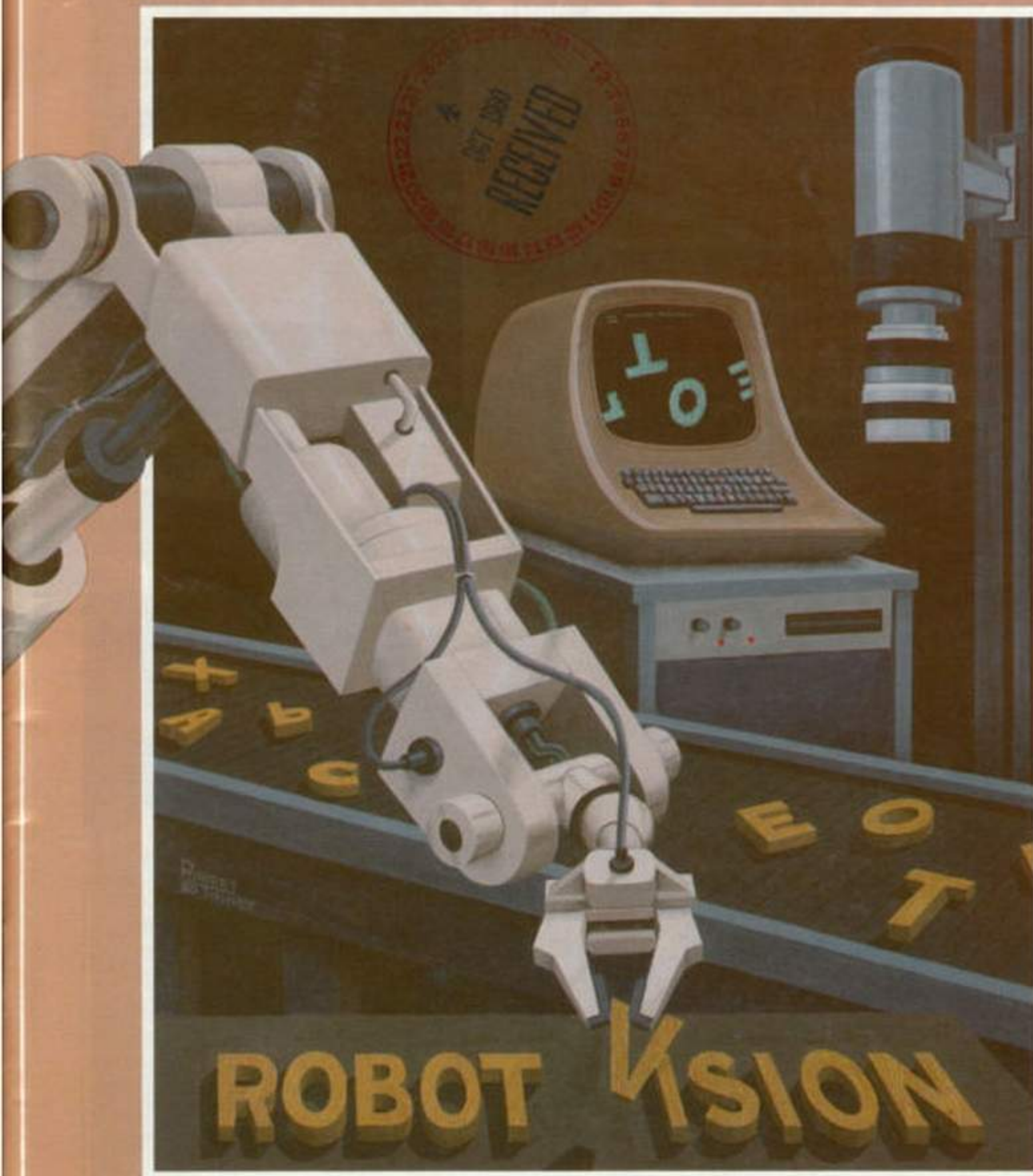
MiniMover 5
Cuk Converter
Industrial Robots

ROBOTICS AGE™

The Journal of Intelligent Machines™

• Fall 1980 •

\$2.50 USA / \$2.90 Canada

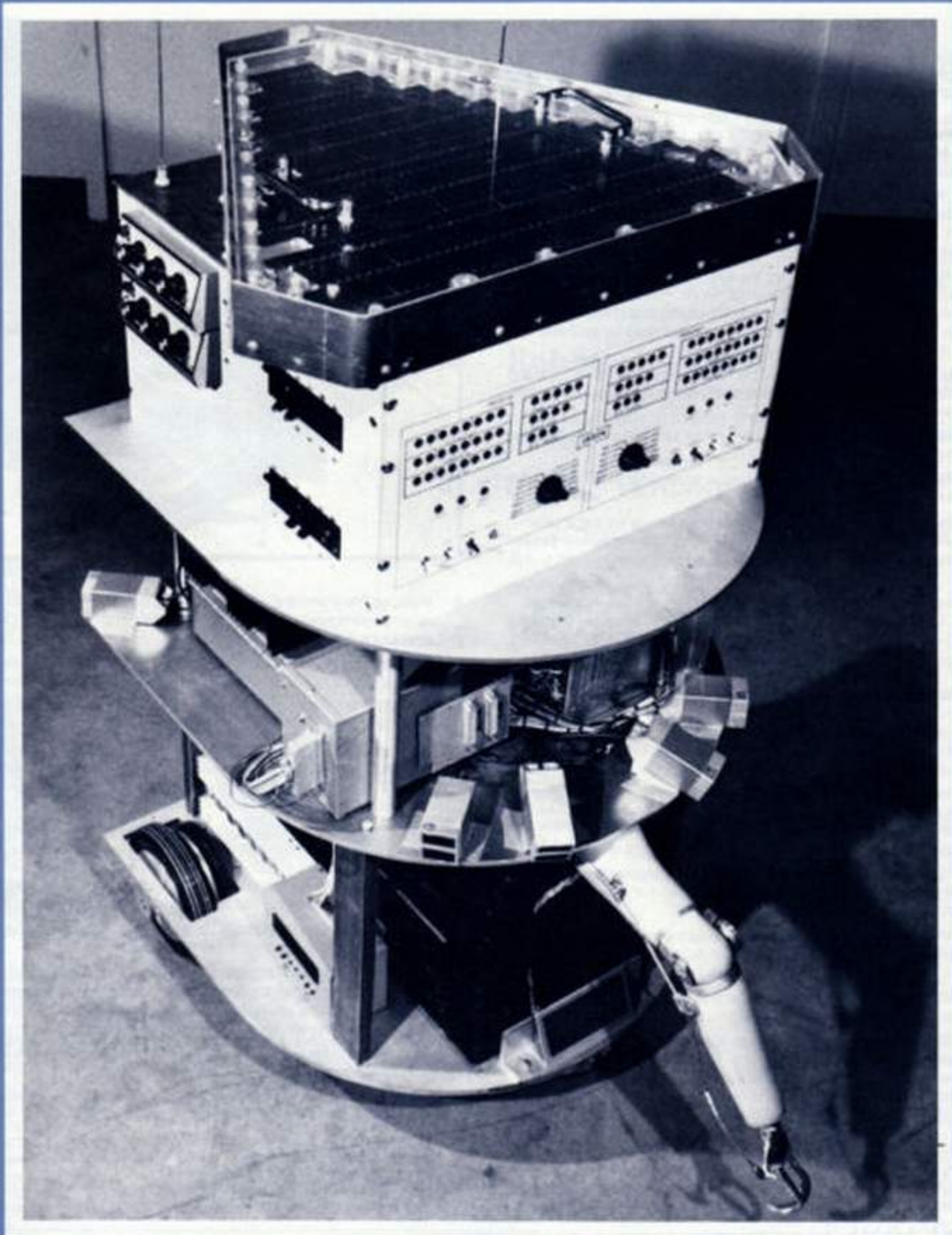


ROBOTICS AGE™

The Journal of Intelligent Machines™

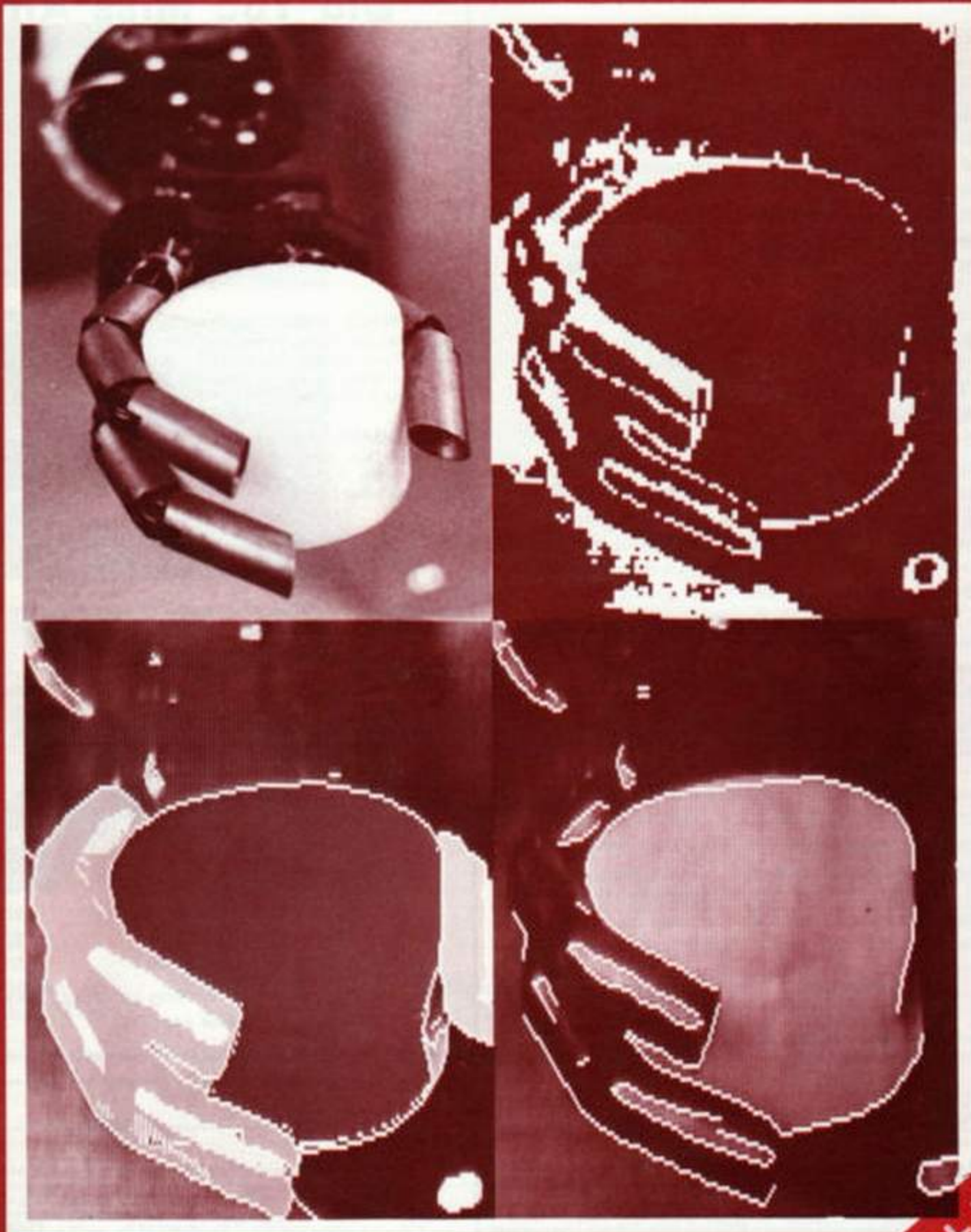
• JAN/FEB 1981

• \$3.00 USA/\$3.50 Canada



ROBOTICS AGE™

The Journal of Intelligent Machines™ • MAR/APR 1991 • \$3.00 USA/\$3.50 CANADA



SPECIAL ISSUE:
Microcomputer
Vision

ROBOTICS AGE™

The Journal of Intelligent Machines™ • MAY/JUNE 1981 • \$3.00 USA/\$3.50 CANADA

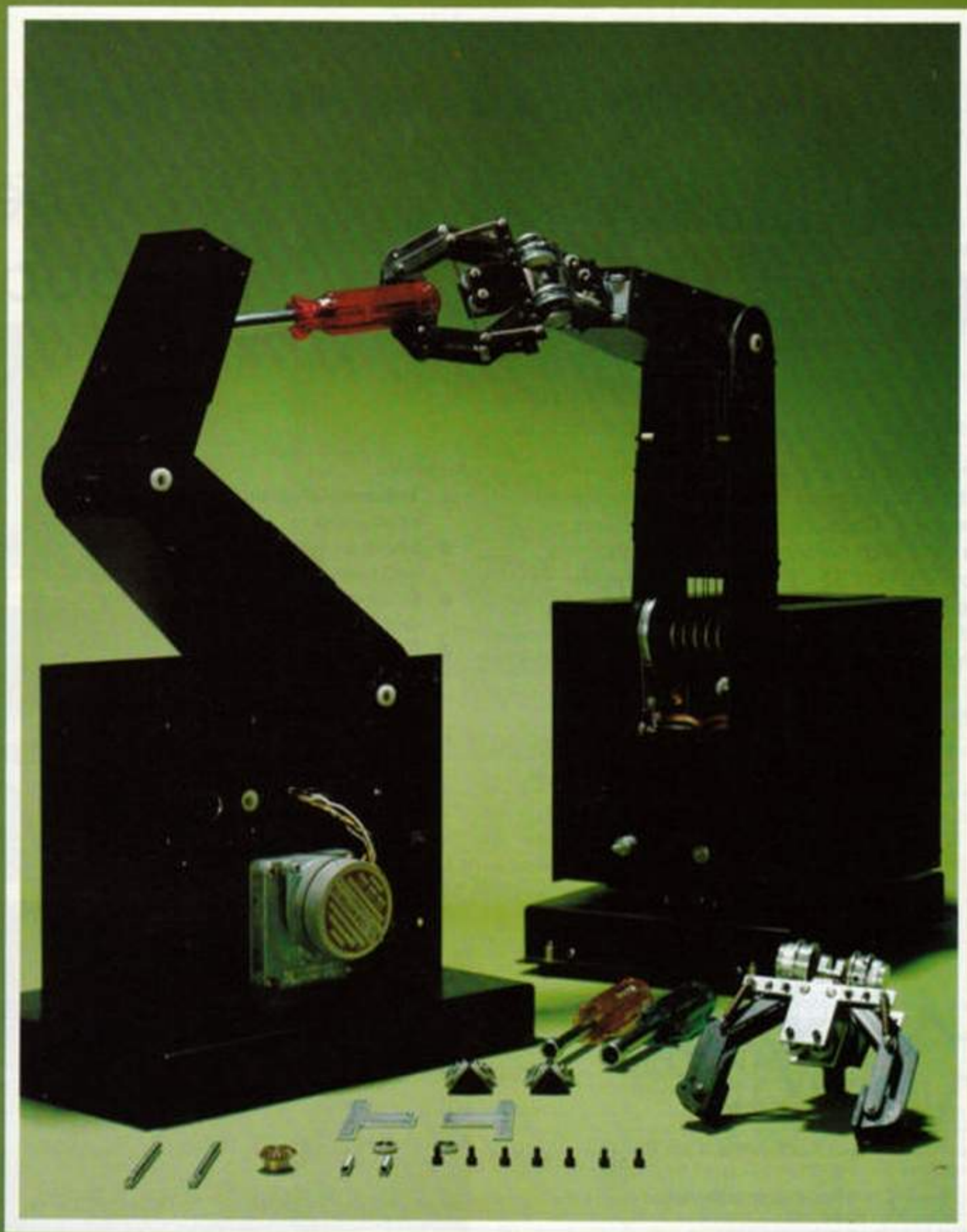
Computerized Lathe
Rosen Interview
Superkim Meets ET-2

Rehabilitative
Robots



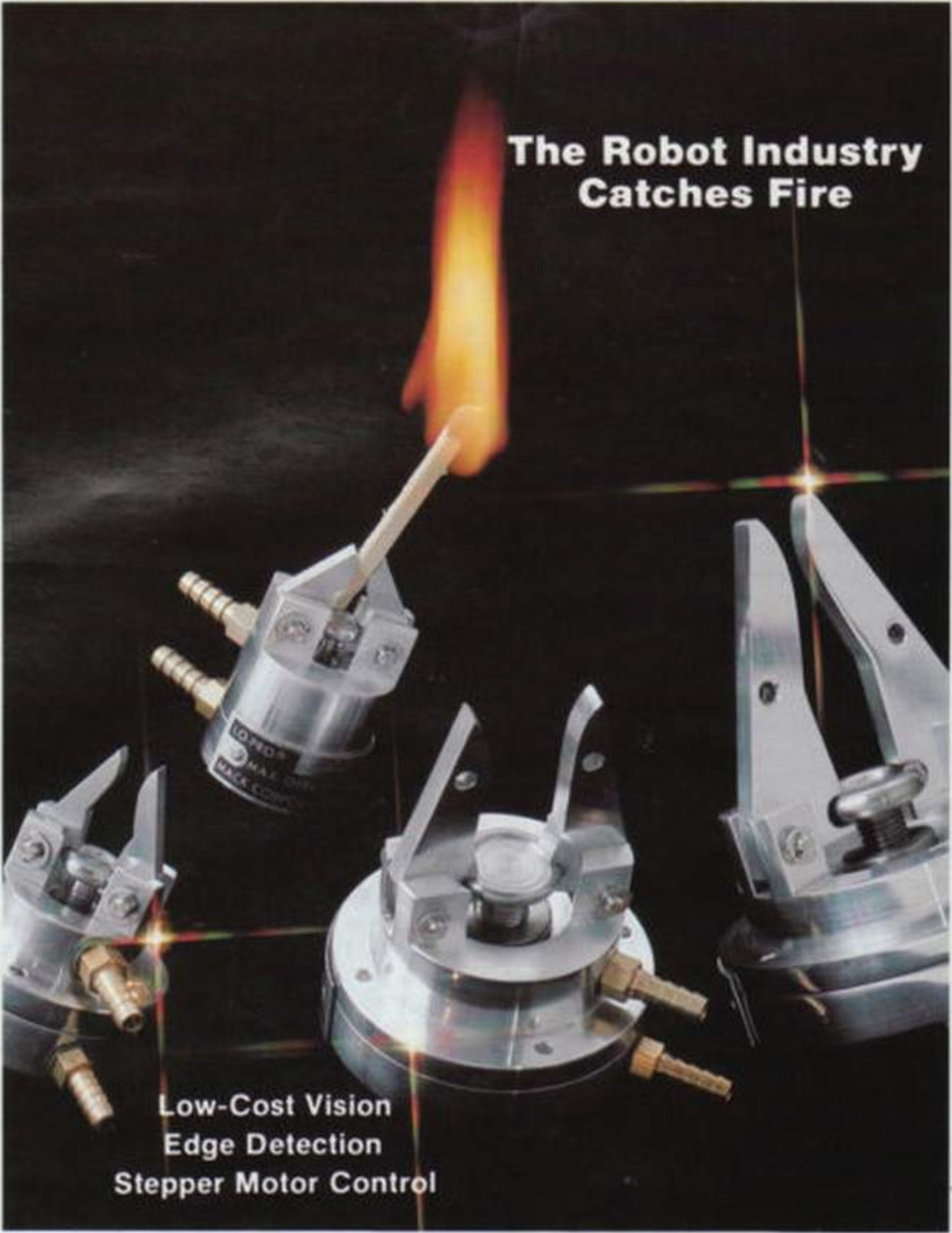
ROBOTICS AGE™

The Journal of Intelligent Machines™ • JULY/AUG 1981 • \$3.00 USA/\$3.50 CANADA



ROBOTICS AGE TM

The Journal of Intelligent Machines™ • SEPT/OCT 1981 • \$3.00 USA/\$3.50 CANADA



The Robot Industry Catches Fire

Low-Cost Vision
Edge Detection
Stepper Motor Control

ROBOTICS AGETM

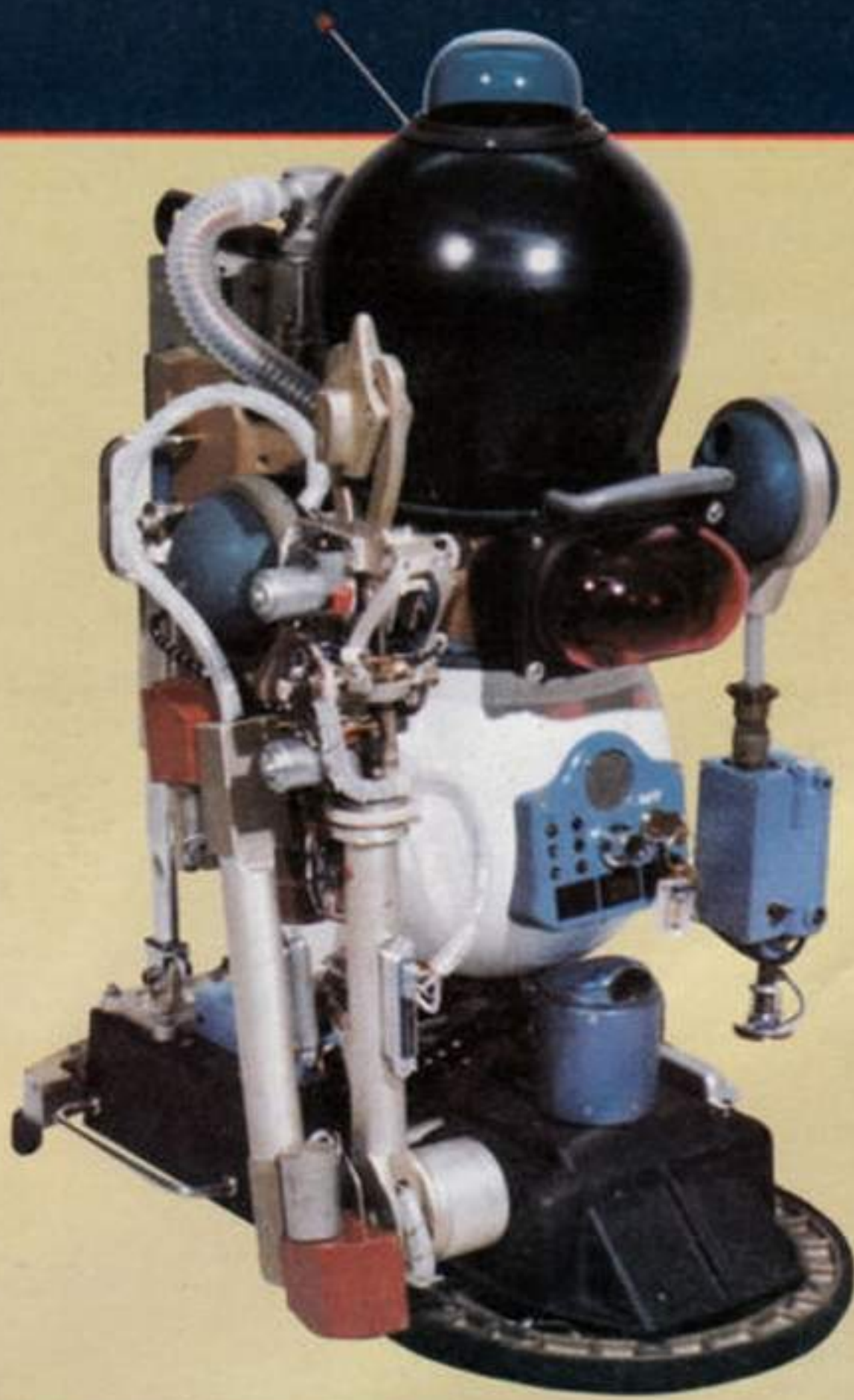
The Journal of Intelligent Machines™ • NOV/DEC 1981 • \$3.00 USA/\$3.50 CANADA

**TEACH
YOUR ROBOT
TO SPEAK**



THE JOURNAL OF INTELLIGENT MACHINES

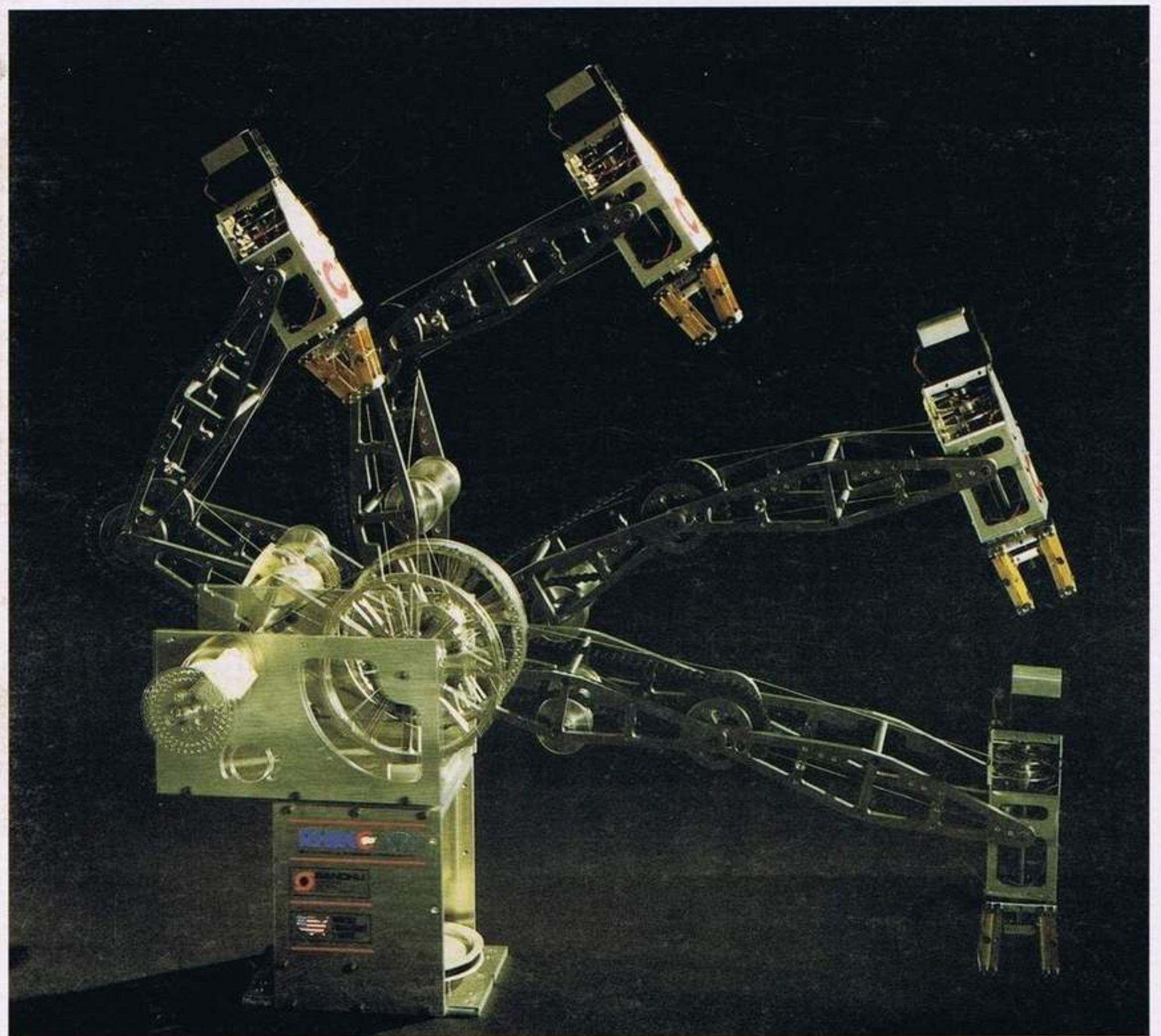
ROBOTICS AGE™



INTRODUCING THE NEW ROBOTICS AGE

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGETM



THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



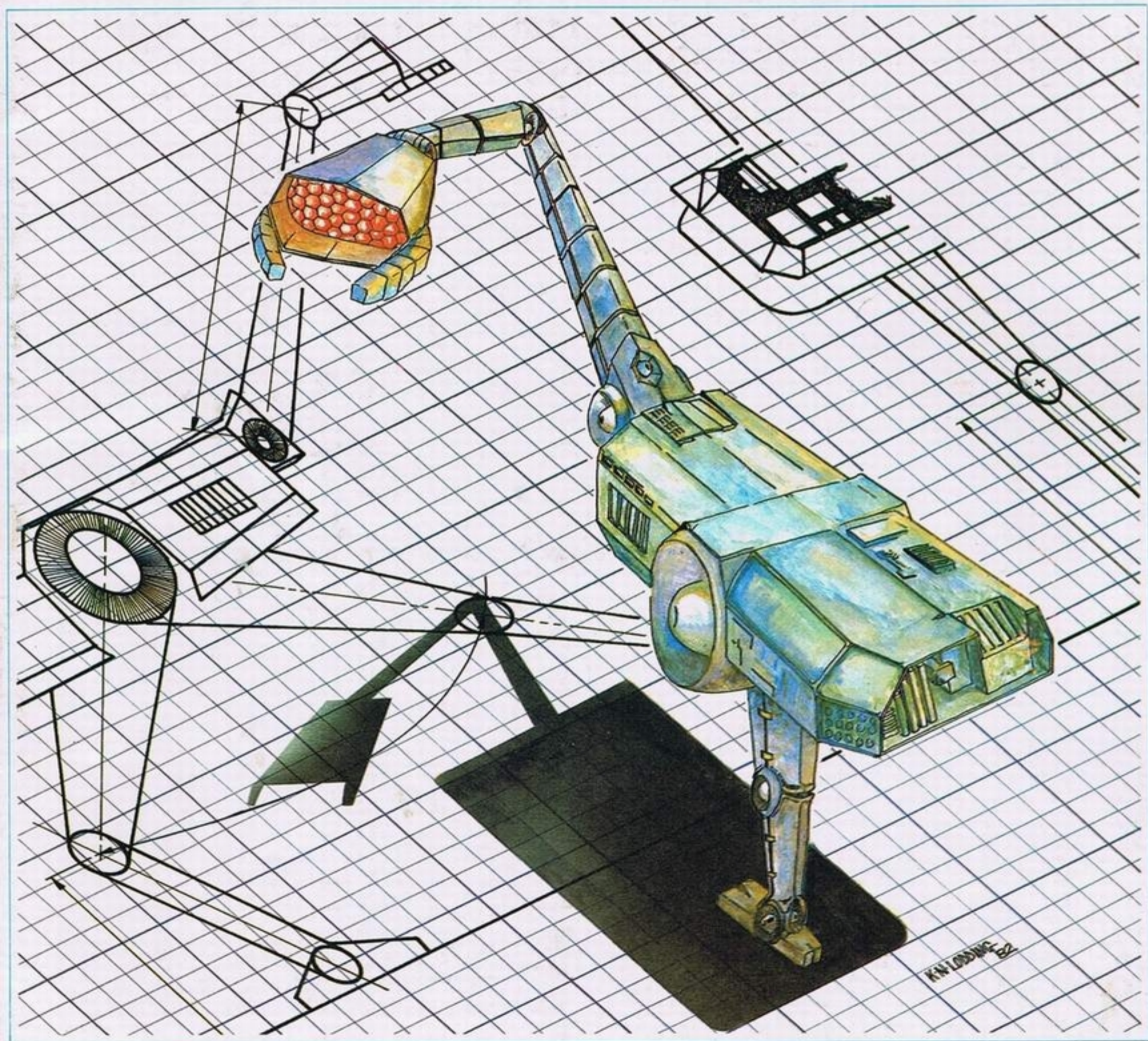
THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



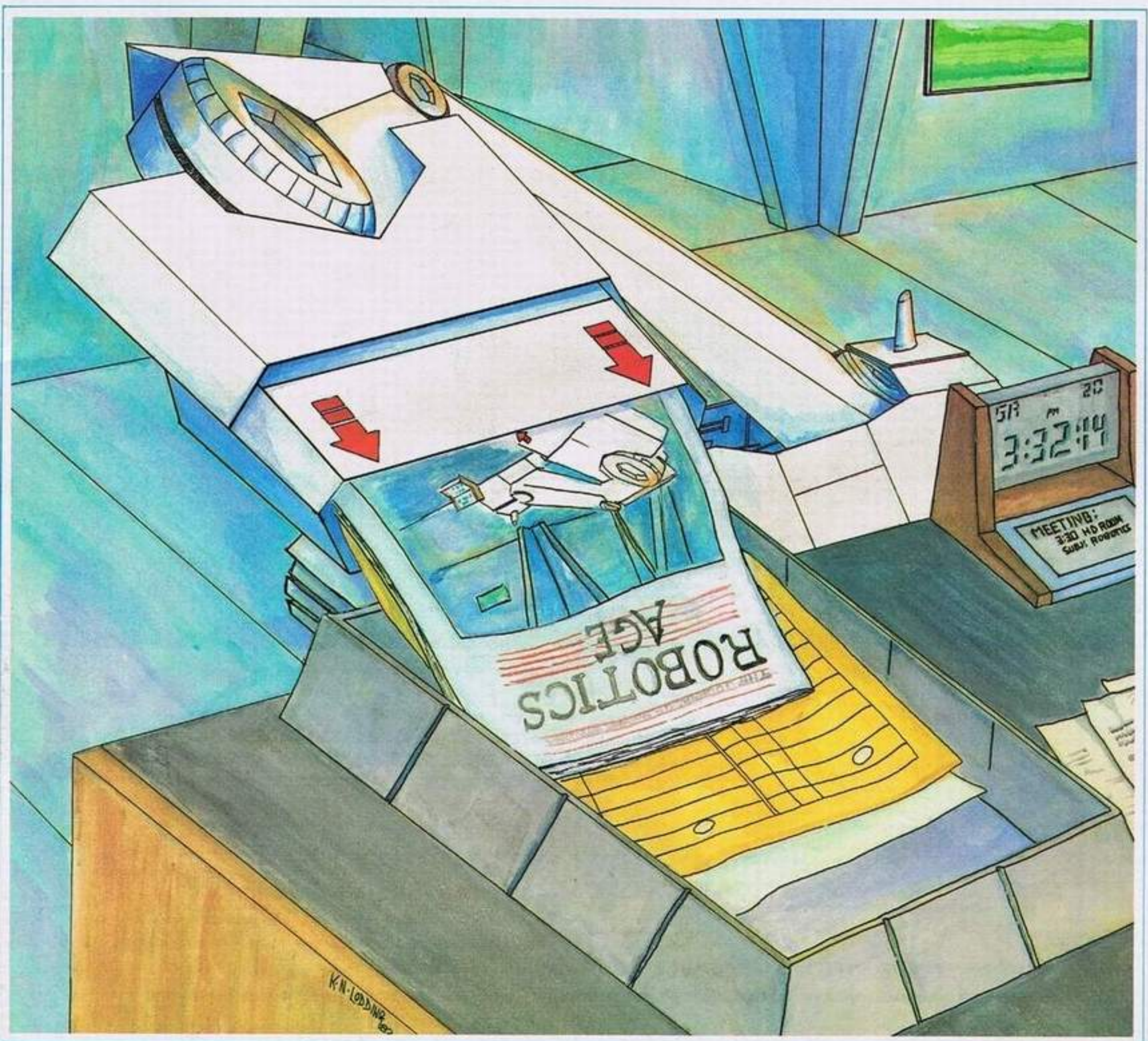
THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



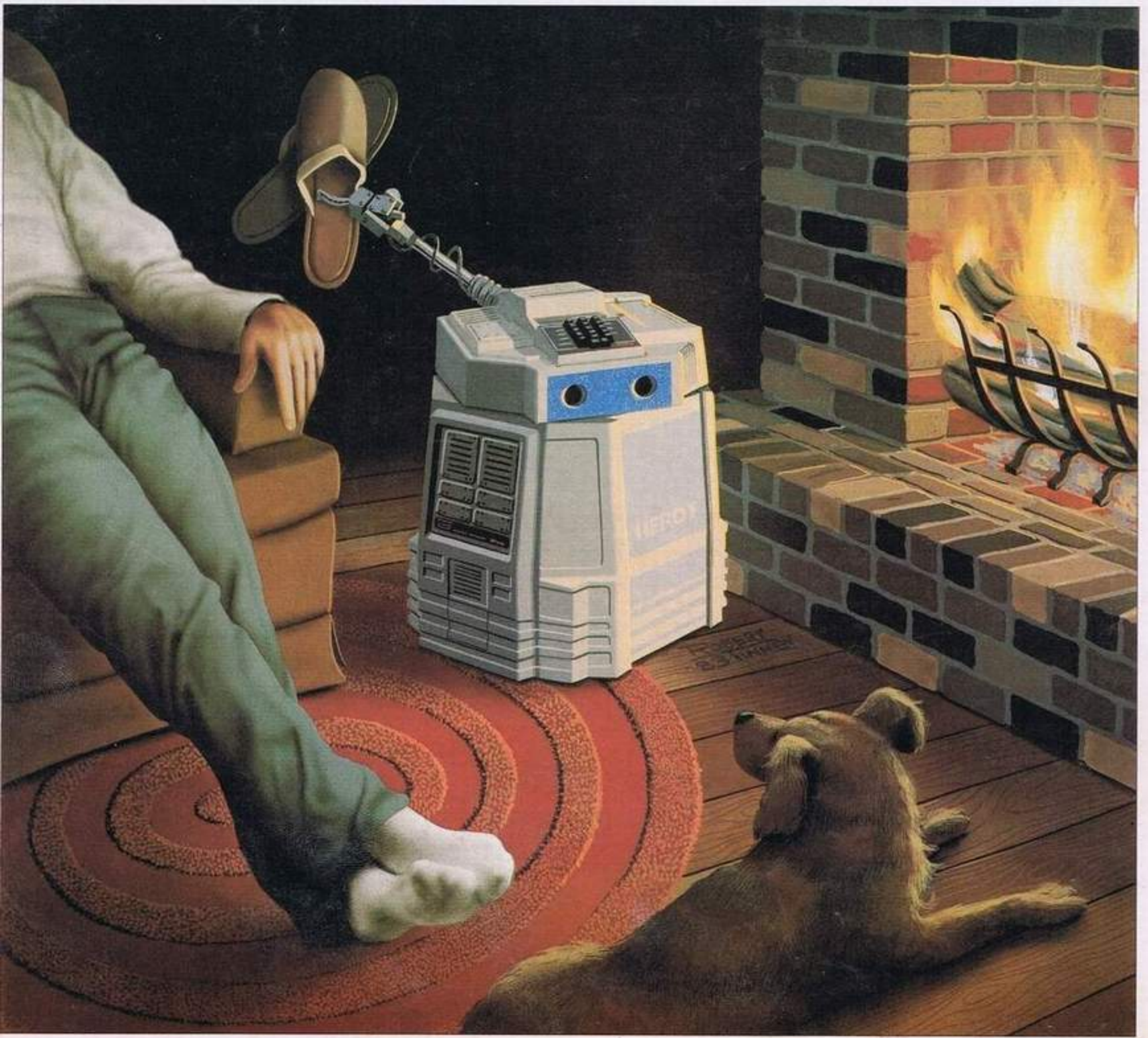
THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



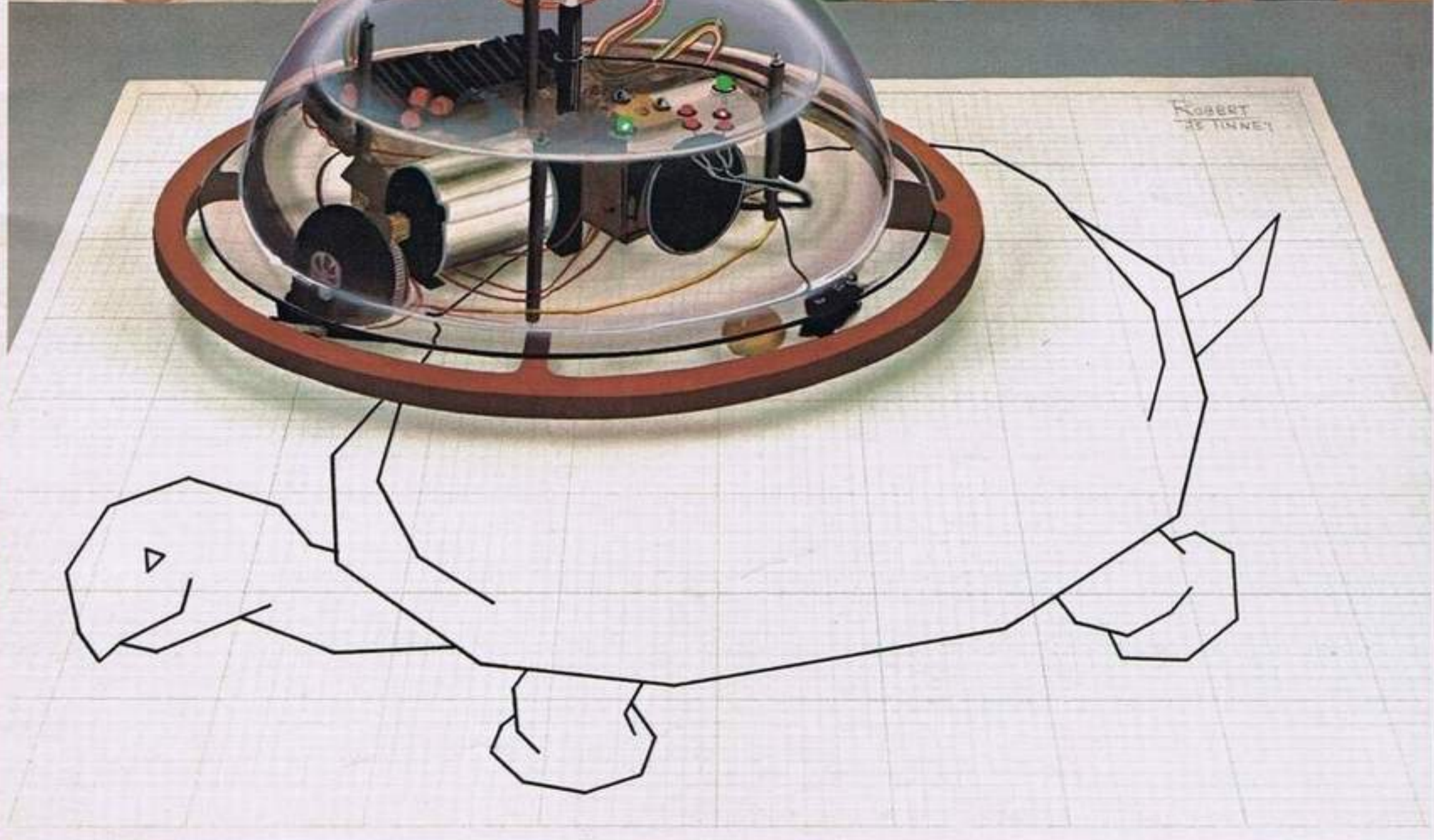
THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



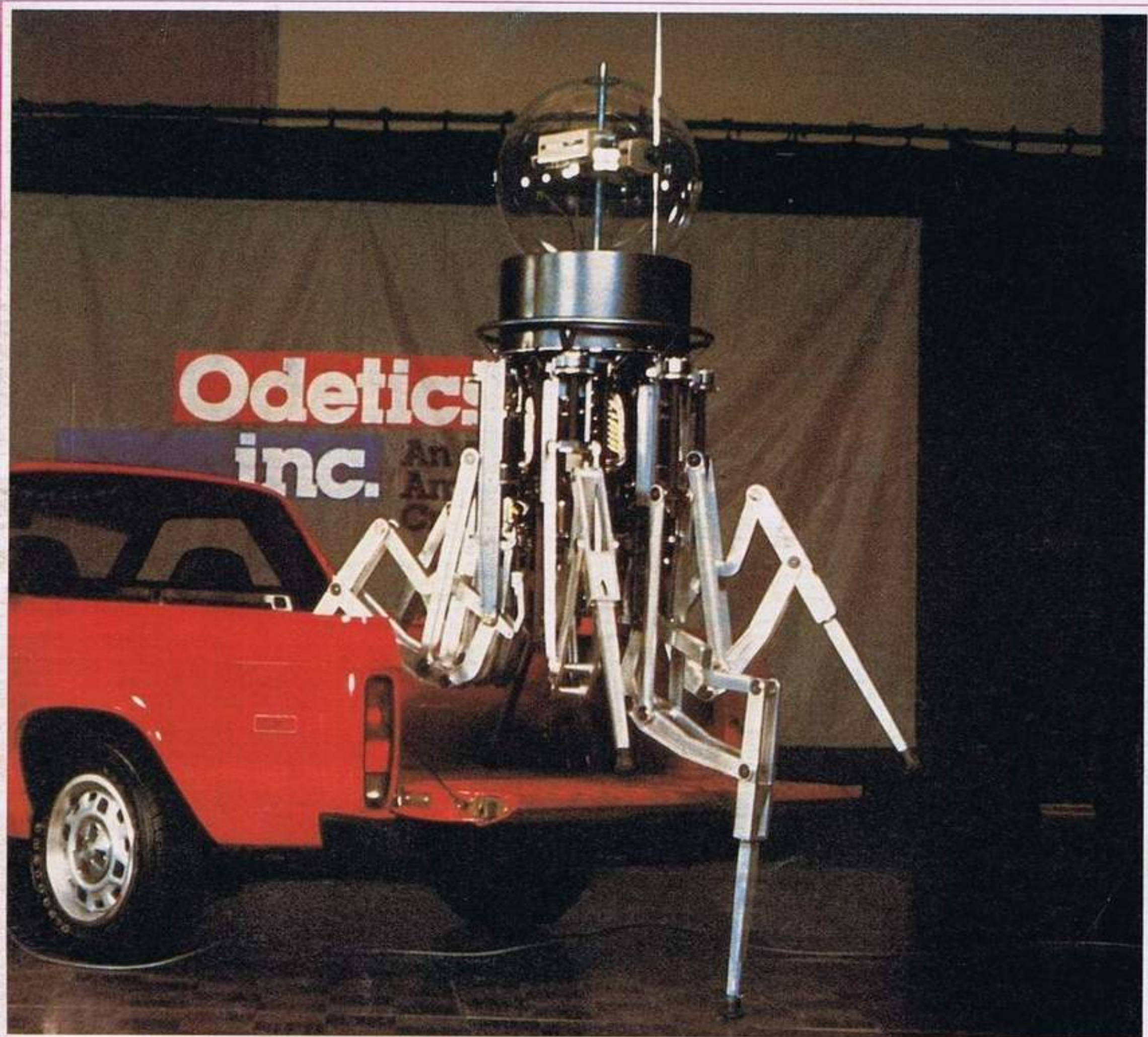
THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



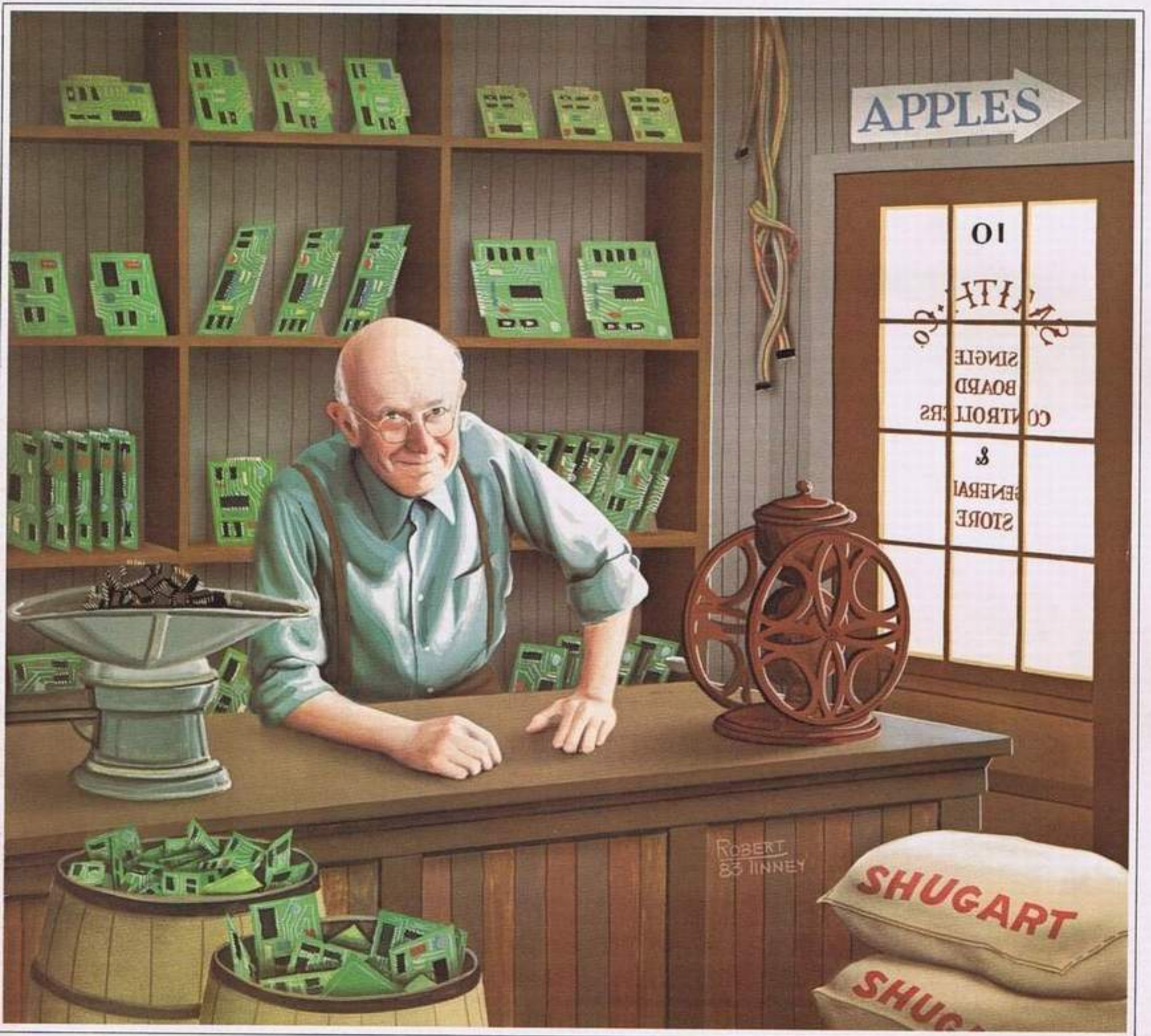
THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™



THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE™

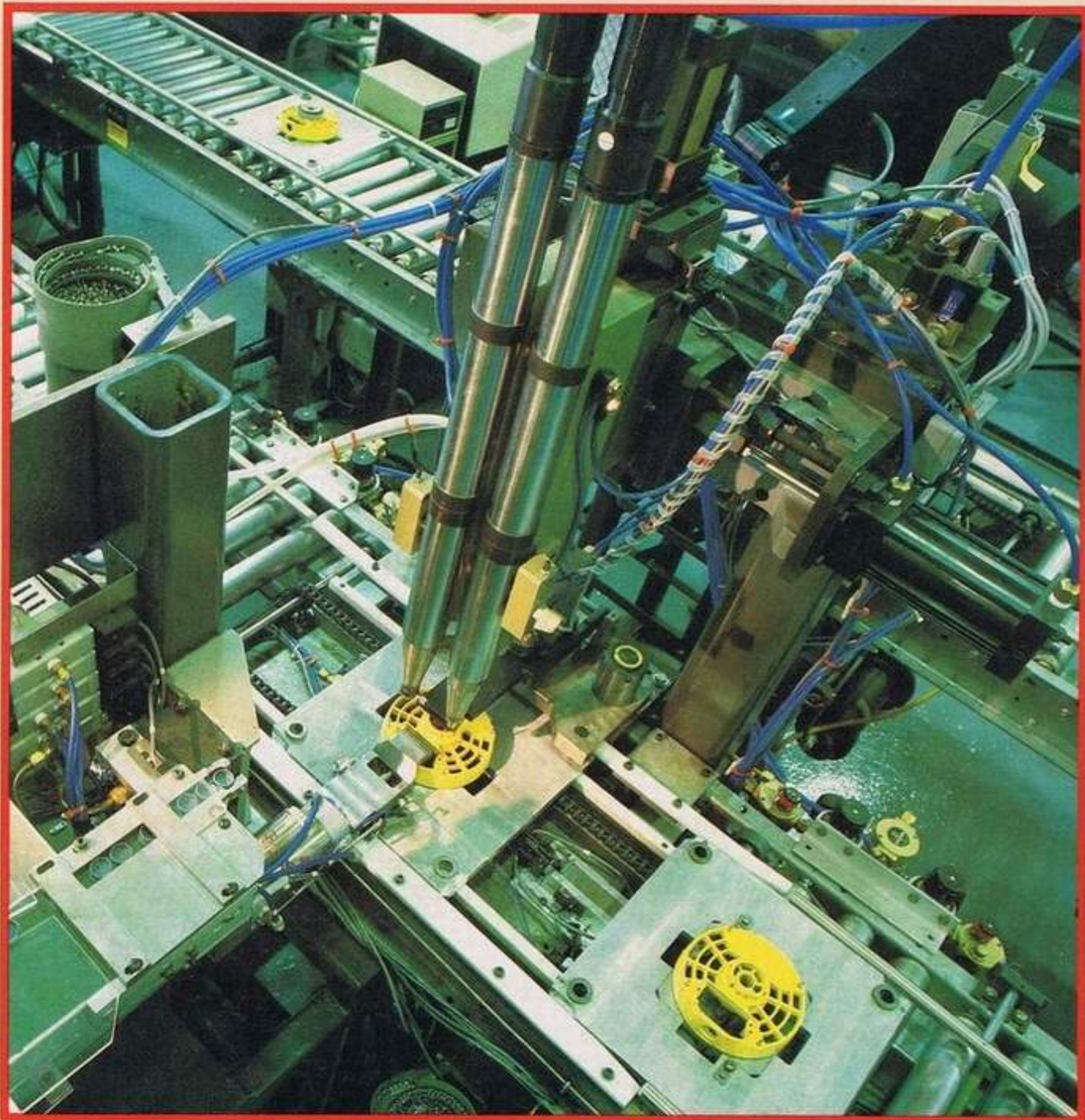


THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE

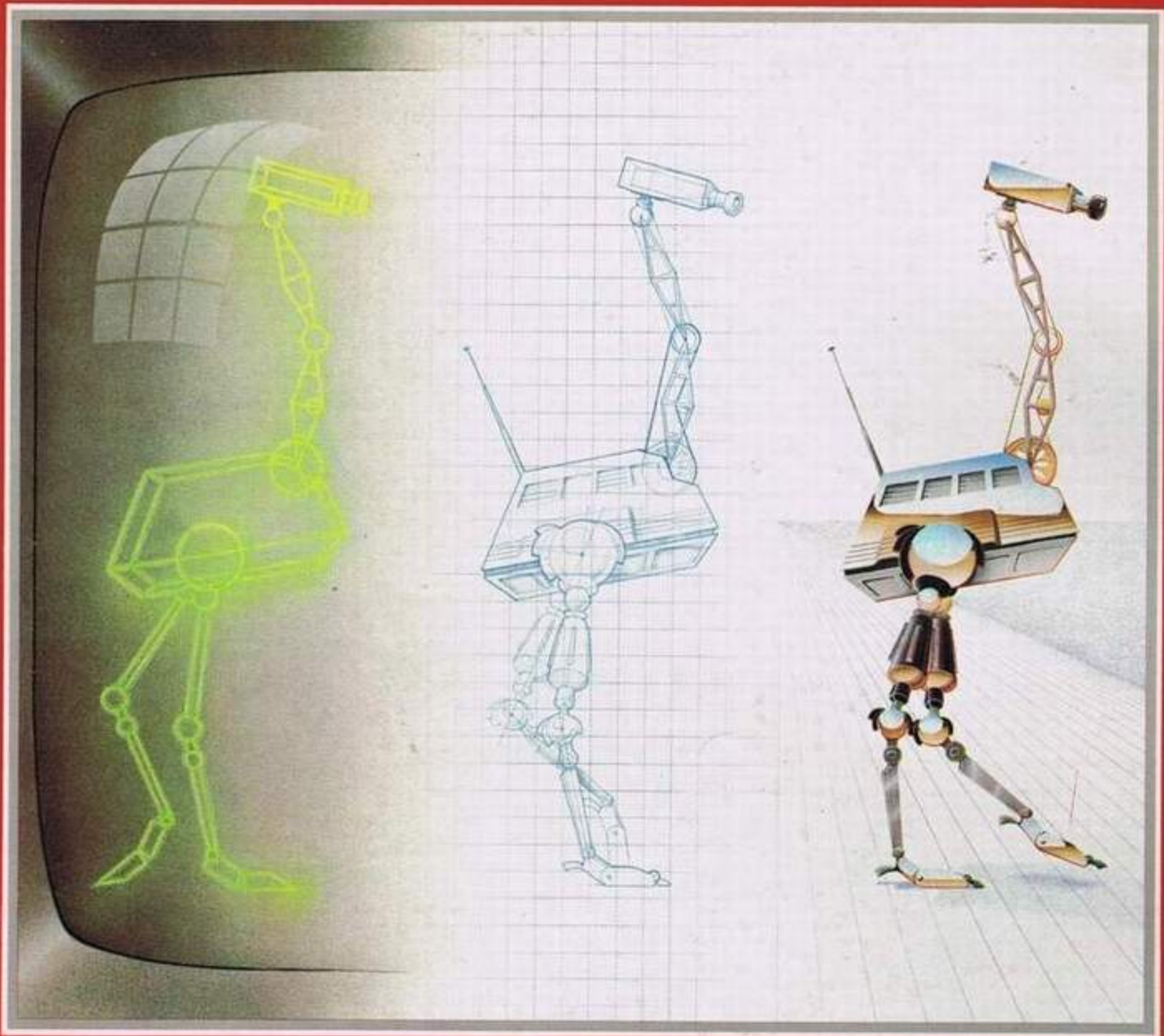


THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE

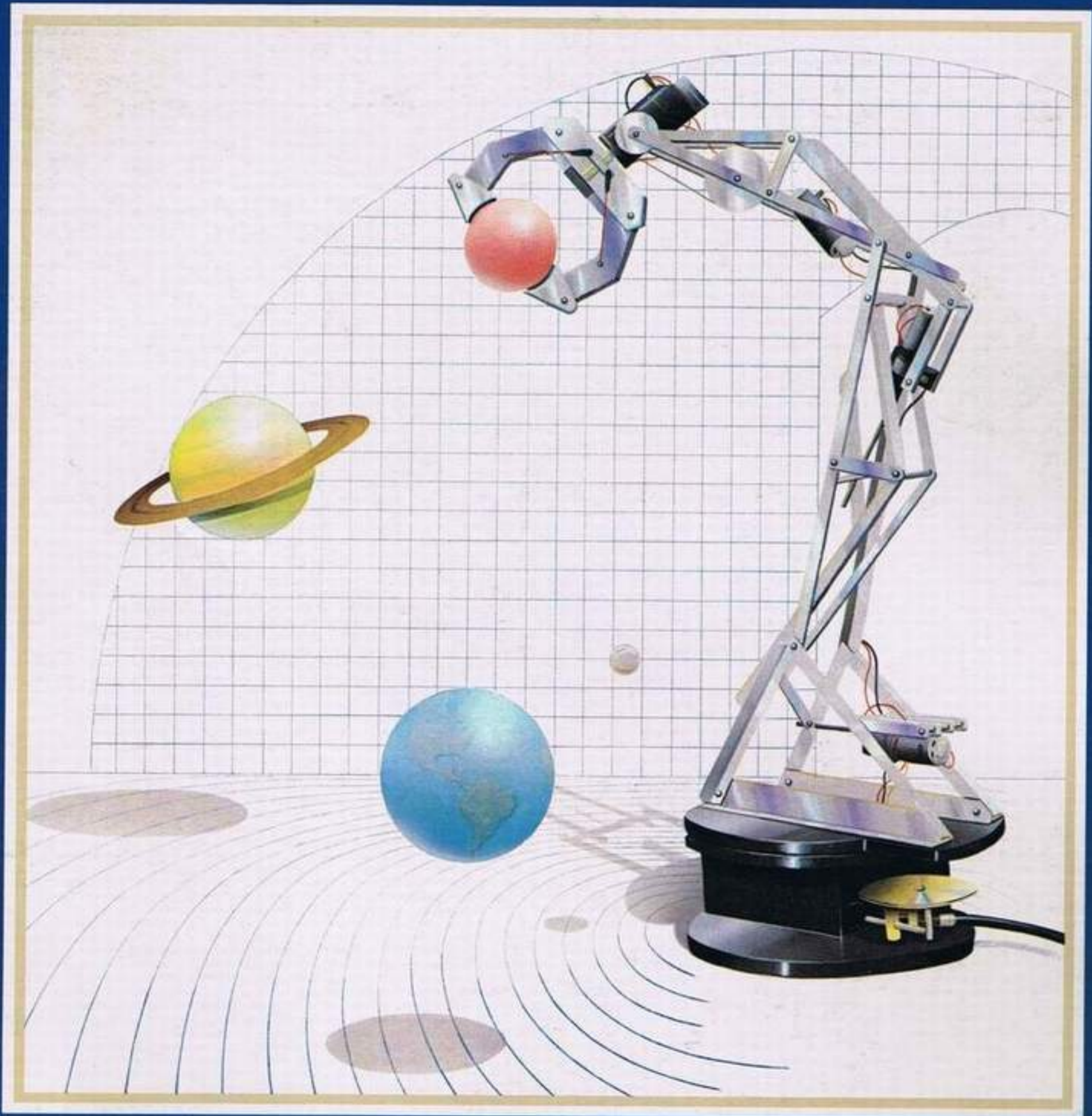


THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE

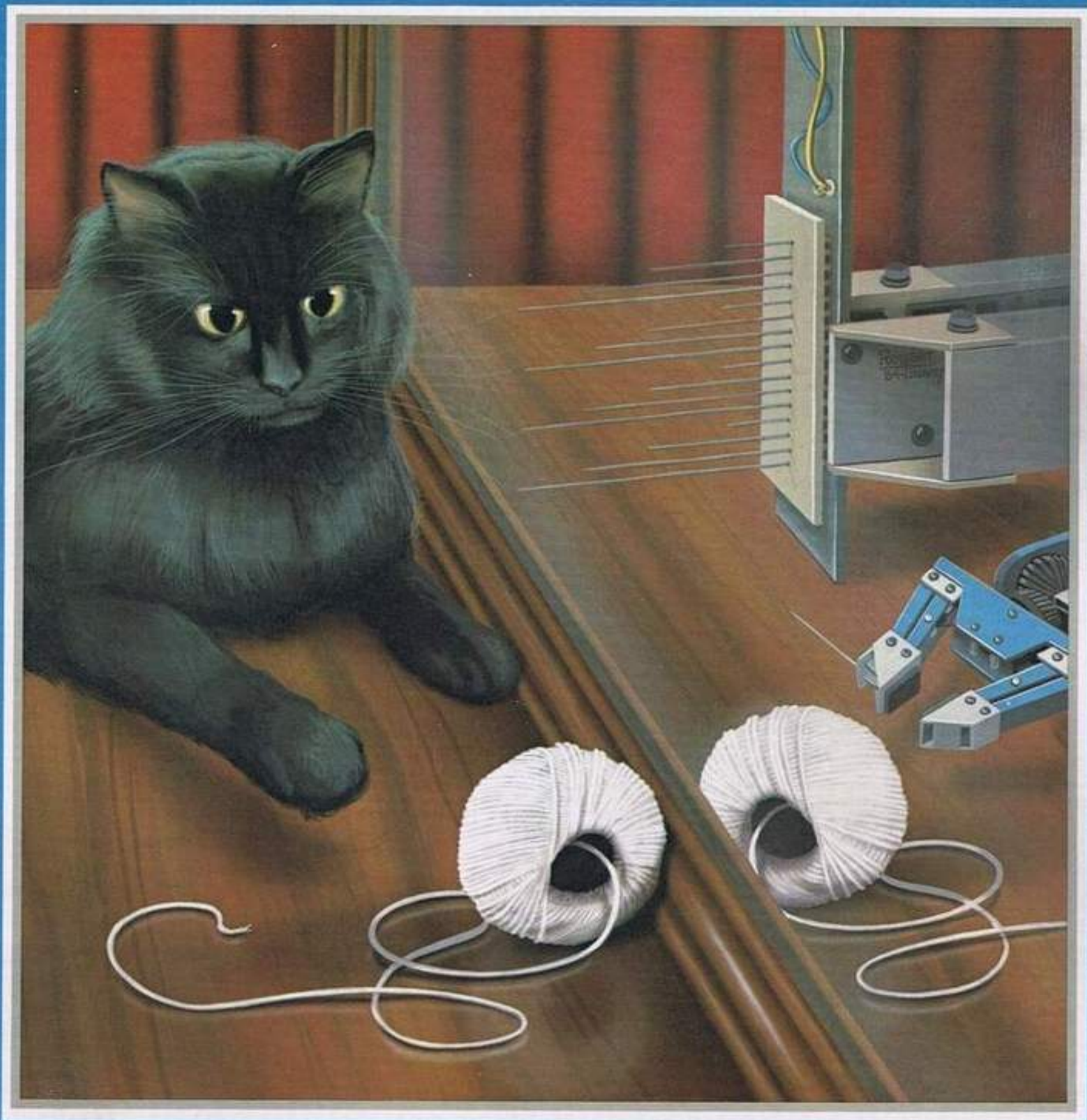


THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE

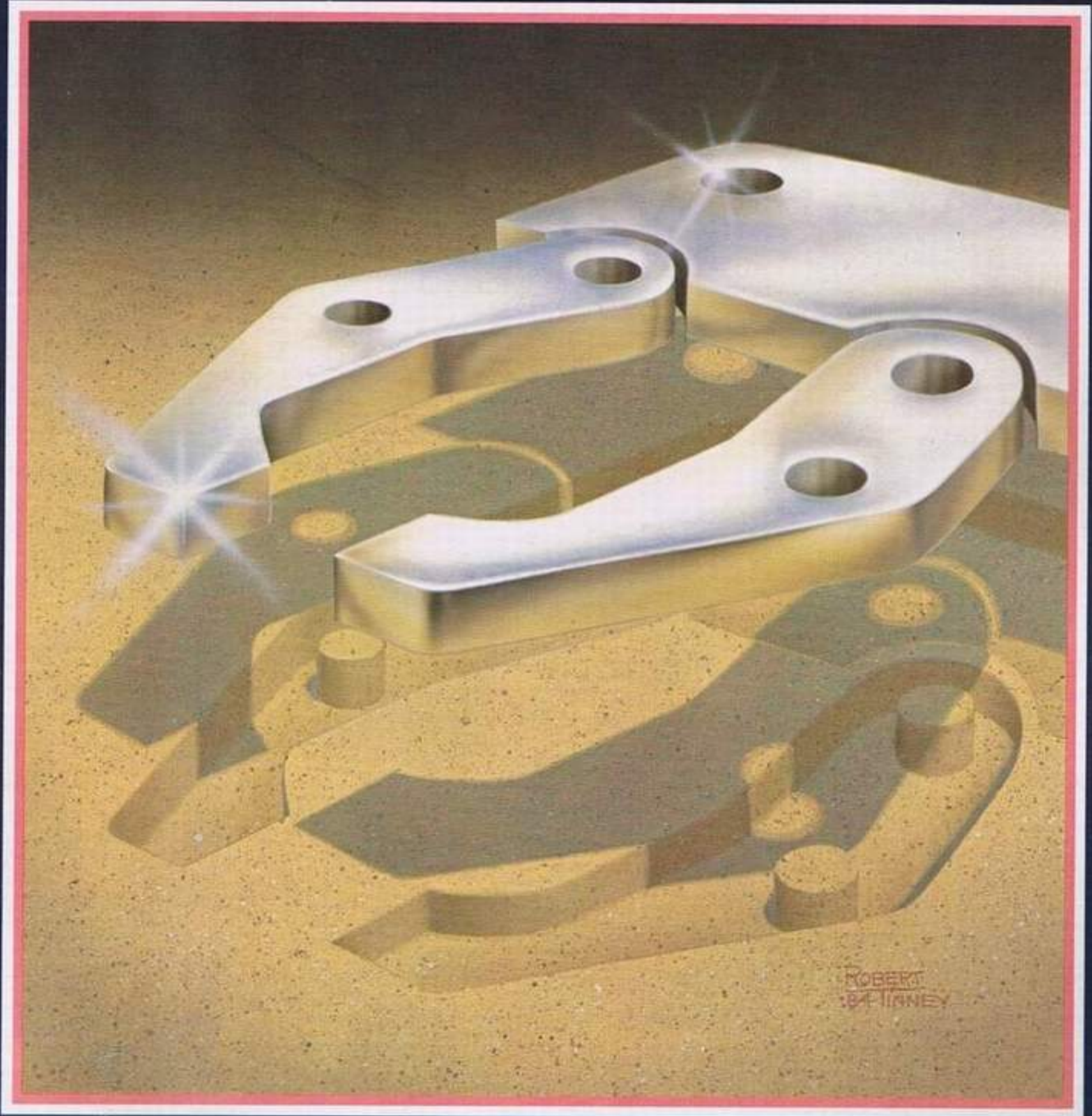


THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE



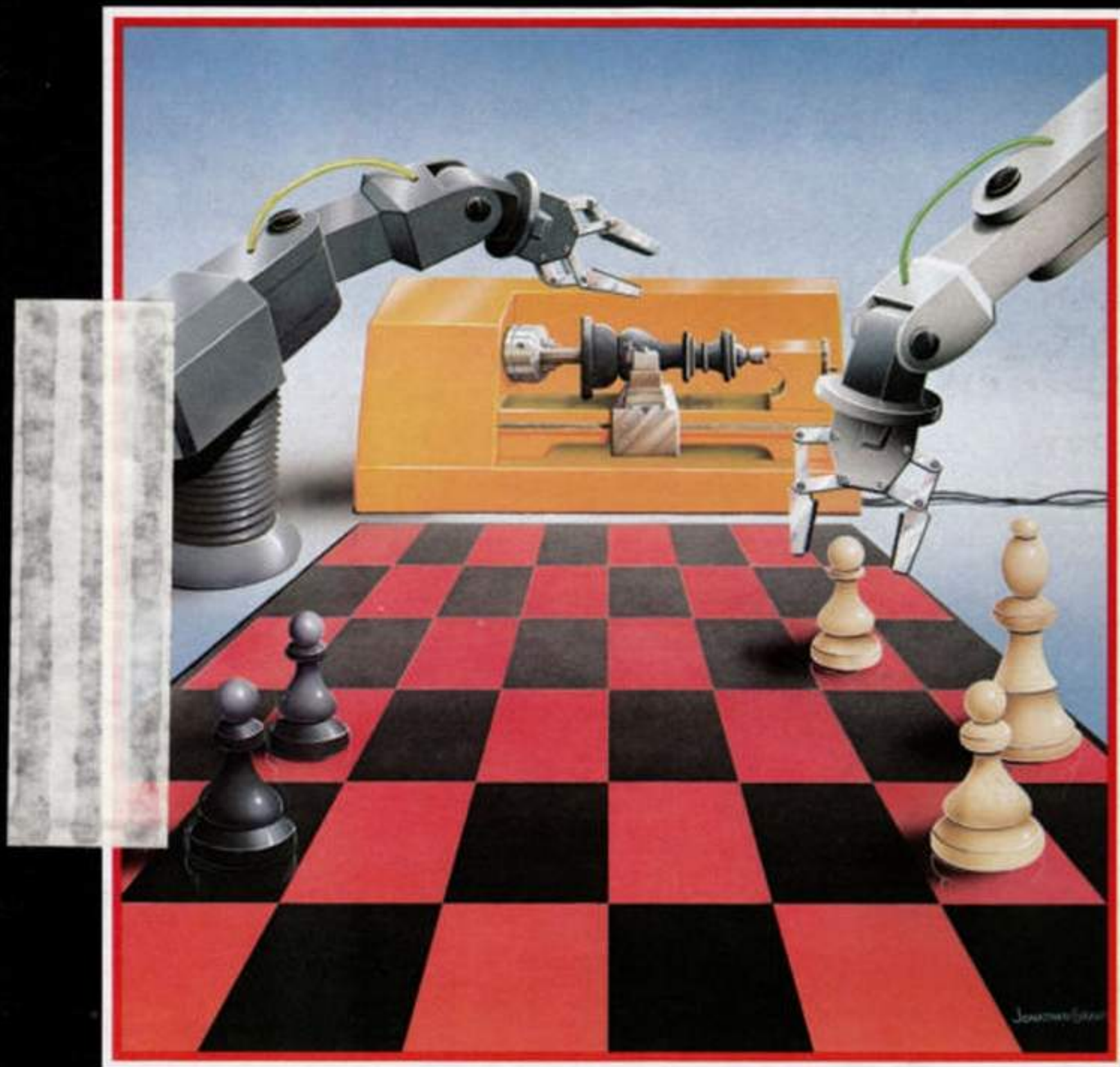
ROBERT
B. TIRNEY

JUNE 1984 VOL. 6 NO. 6

\$3.00 USA/\$3.50 CANADA

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE

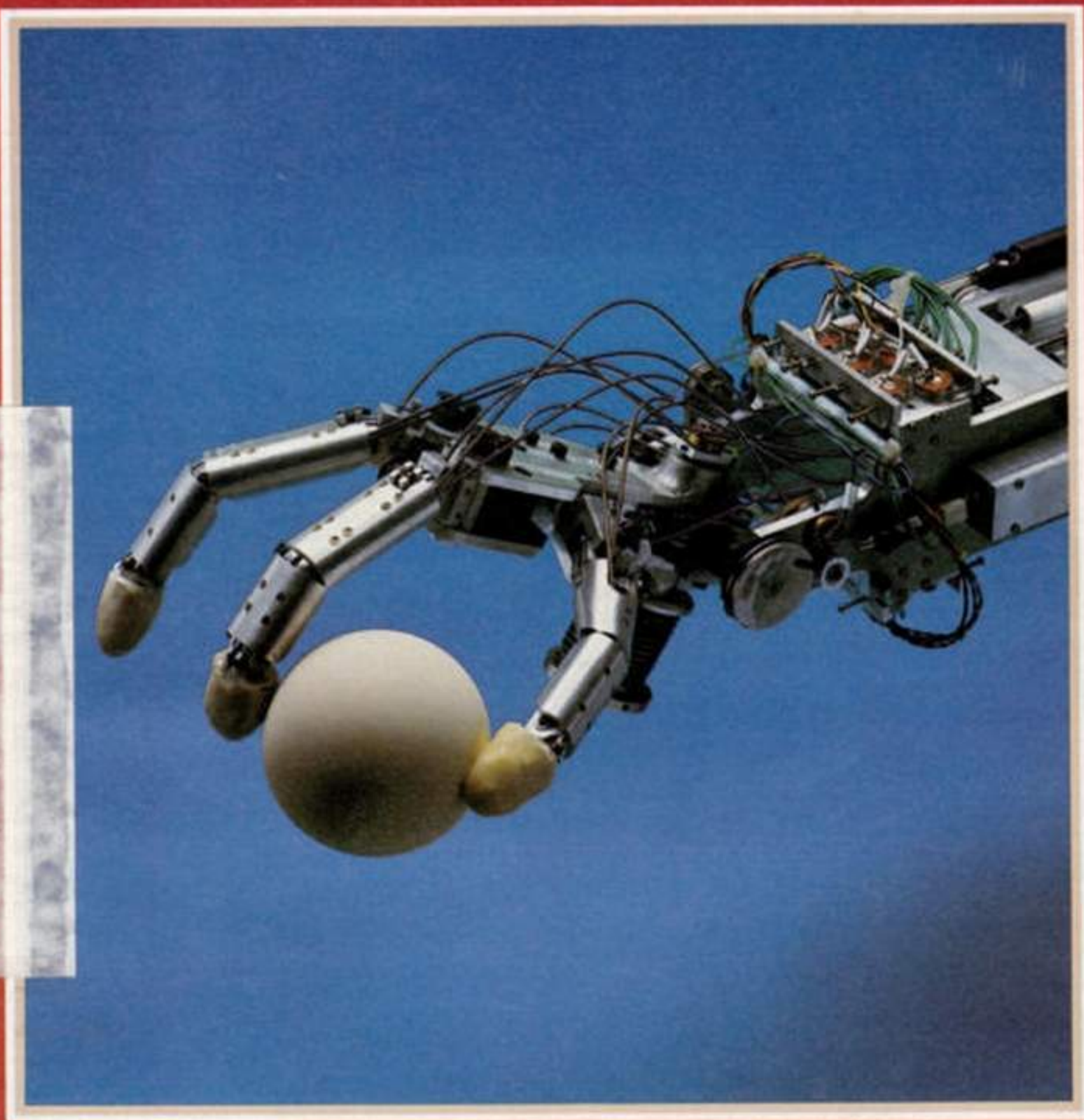


JULY 1984 VOL. 6 NO. 7

\$3.00 USA/\$3.50 CANADA

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE



THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE

THE BEGINNING FOR PERSONAL ROBOTICS?



THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS AGE

ROBOTS AND EDUCATION



Real-World Data Acquisition Systems

OCTOBER 1984 VOL. 6 NO. 10

\$3.00 USA/\$3.50 CANADA

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE



ROBOTICSTM

AGE



ROBOTICSTM

AGE



Innovation in Locomotion

JANUARY 1985 VOL. 7 NO. 1

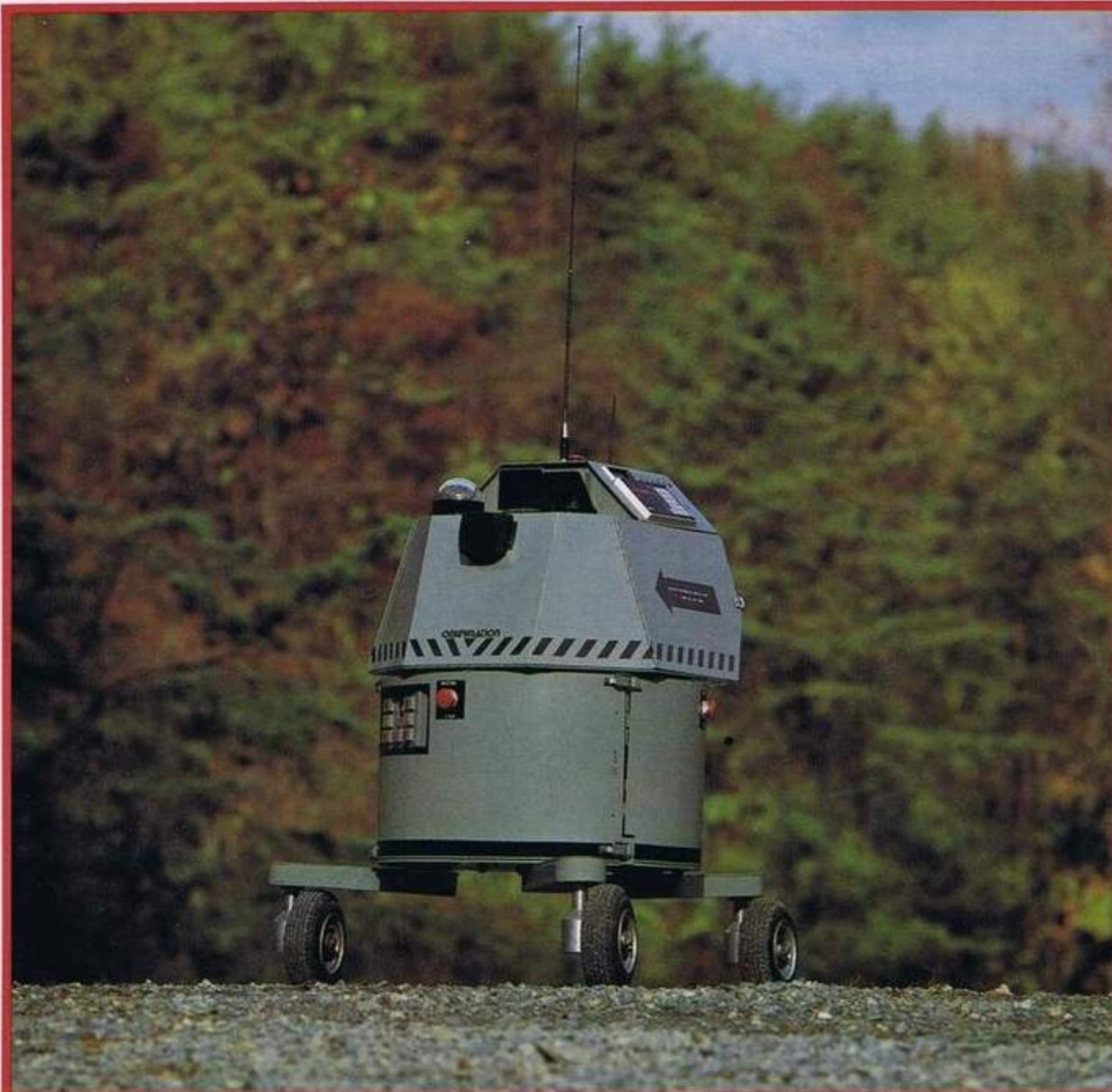
\$3.00 USA/\$3.50 CANADA

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICS

TM

AGE



GEMINI: First of a New Breed

FEBRUARY 1985 VOL. 7 NO. 2

\$3.00 USA/\$3.50 CANADA

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTICSTM

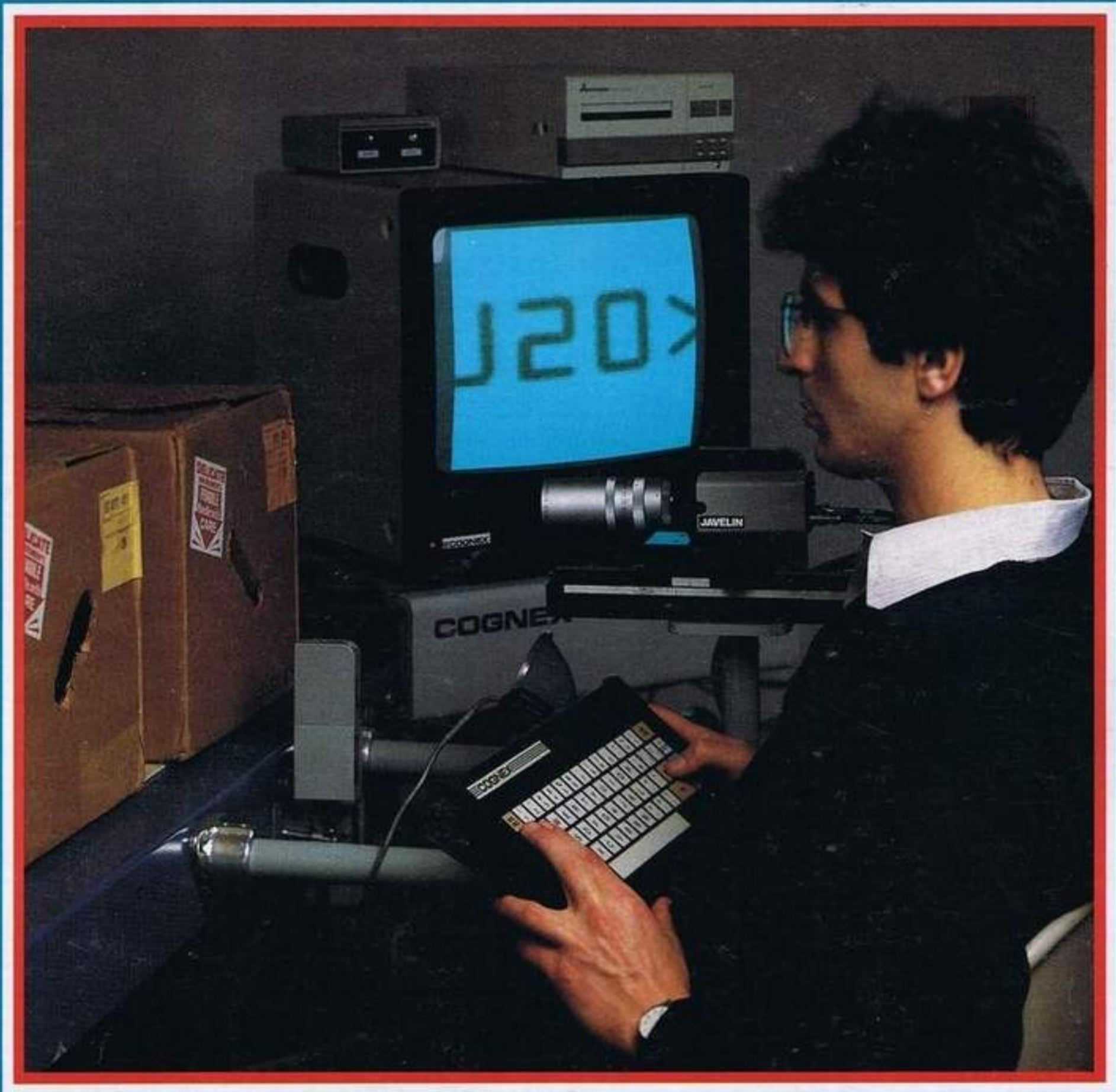
AGE



ROBOTICS

TM

AGE

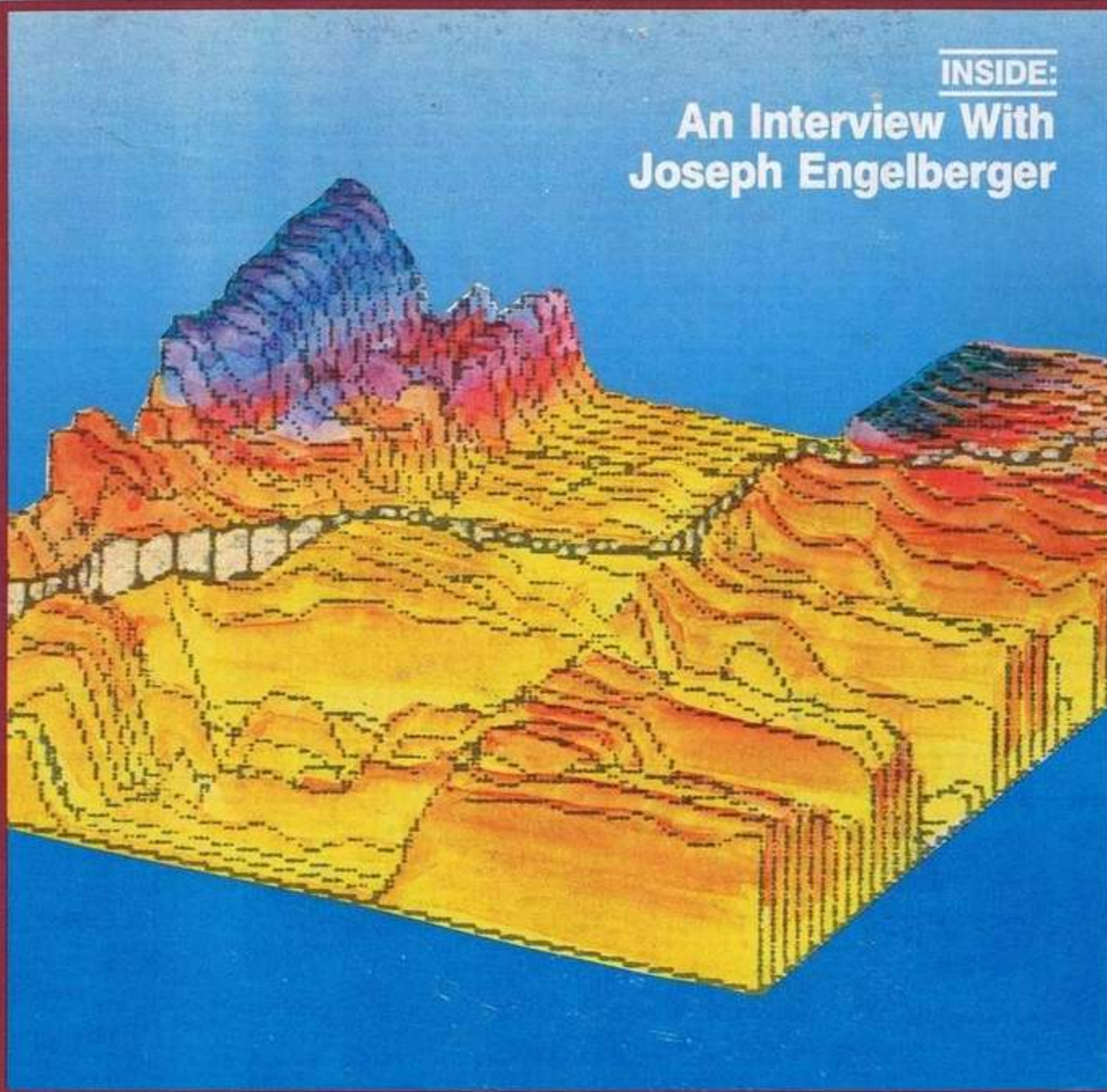


ROBOTICSTM

AGE

INSIDE:

**An Interview With
Joseph Engelberger**



ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES



NEW DIMENSIONS IN FMS

Interchangeable End Effectors
 Gripper Design Research
 XY Positioning

ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES



SHOULD YOU AUTOMATE?

A Step-by-Step
Evaluation Method

VISION:

Recognizing
Overlapping Parts

ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES

ROBOTIC SENSING

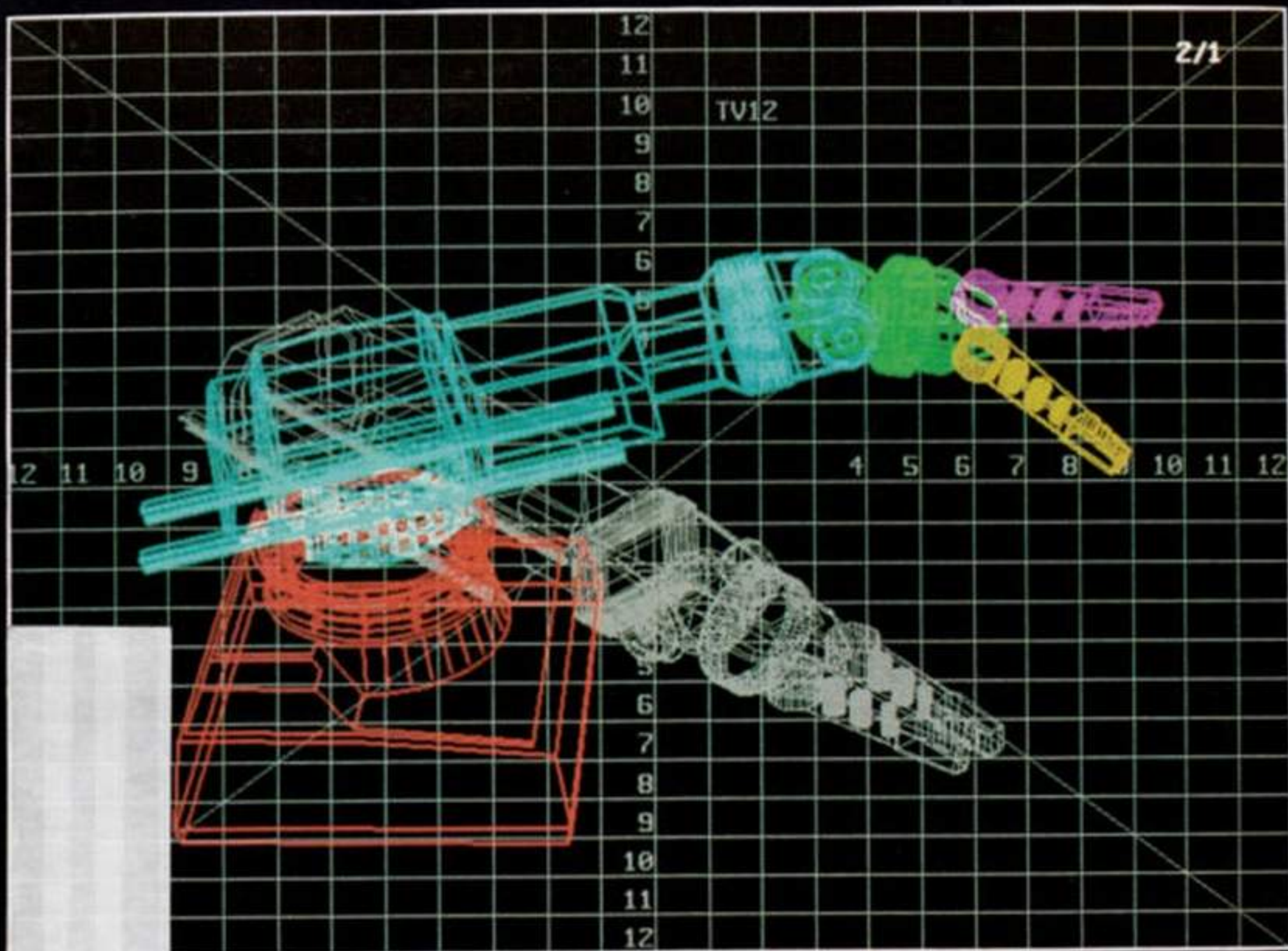
A New Super
Camera for
Vision Systems
Ultrasonic
Ranging
Tactile Sensing:
An Alternative
to Vision?



ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES



**Inverse Robot Kinematic Solutions
The Use of CAD in Robot Systems Design**

ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES

**Robot Control Languages
For Industry and Education**

**Robotics and Industrial Training:
An Overview**



XR SERIES MARK III CONTROLLER
TEACH PENDANT
OUTPUT
POWER
1117

ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES



**Programmable
Controllers**

**Multiple-Arm
Control for
Industrial Robots**

NOVEMBER 1985 VOL. 7 NO. 11

\$3.00 USA/\$3.50 CANADA

ROBOTICS

A G E™

THE JOURNAL OF INTELLIGENT MACHINES

Robotics In The Military
Worldwide Trends In
Robotics



ROBOTICS

A — G — E™

THE JOURNAL OF INTELLIGENT MACHINES



Autonomous Robots
Automatic Guided
Vehicles

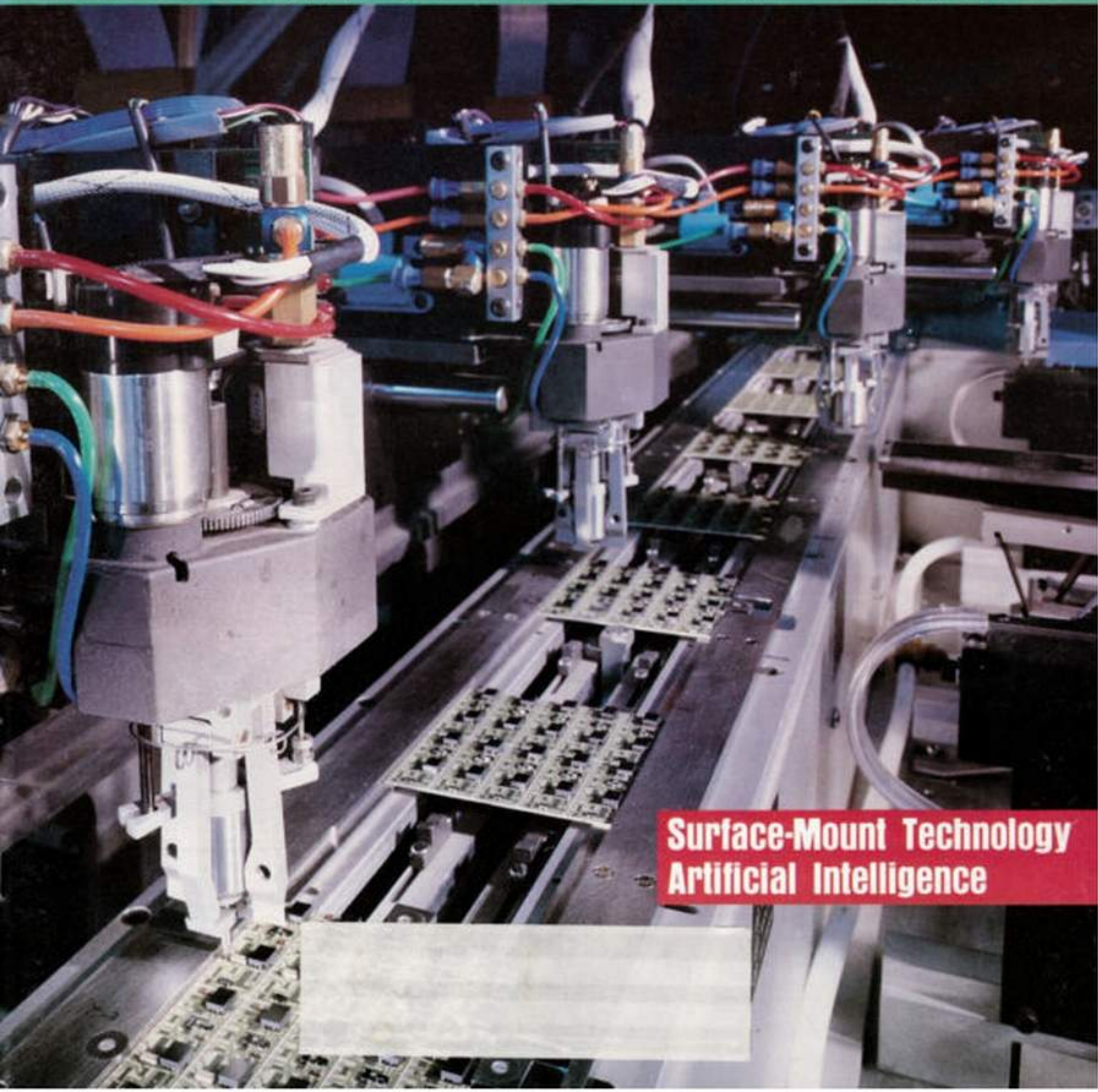
JANUARY 1986 VOL. 8 NO. 1

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



**Surface-Mount Technology
Artificial Intelligence**

FEBRUARY 1986 VOL. 8 NO. 2

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



**End-of-Arm Tooling
Material Handling**

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES

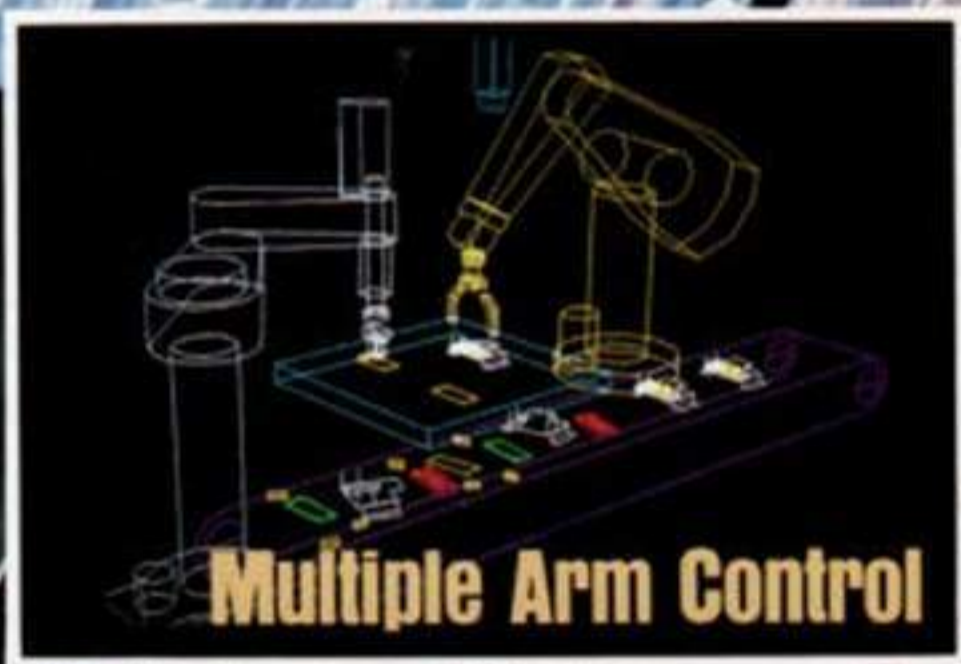


**Robotics in
Hazardous Environments
Robotic Die Casting
Robotics Databases**

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



Robotics in Electronics Assembly
Robot Reliability: A User Speaks Out

MAY 1986 VOL. 8 NO. 5

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



**Robots in
Clean Room
Operations**

**Robot
Control
Software**

**Expert
Systems**

JUNE 1986 VOL. 8 NO. 6

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



**Machine
Vision
Technology**

**Robotic
Welding**

**Inside:
Special
Vision
Technology
Supplement!**

JULY 1986 VOL. 8 NO. 7

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

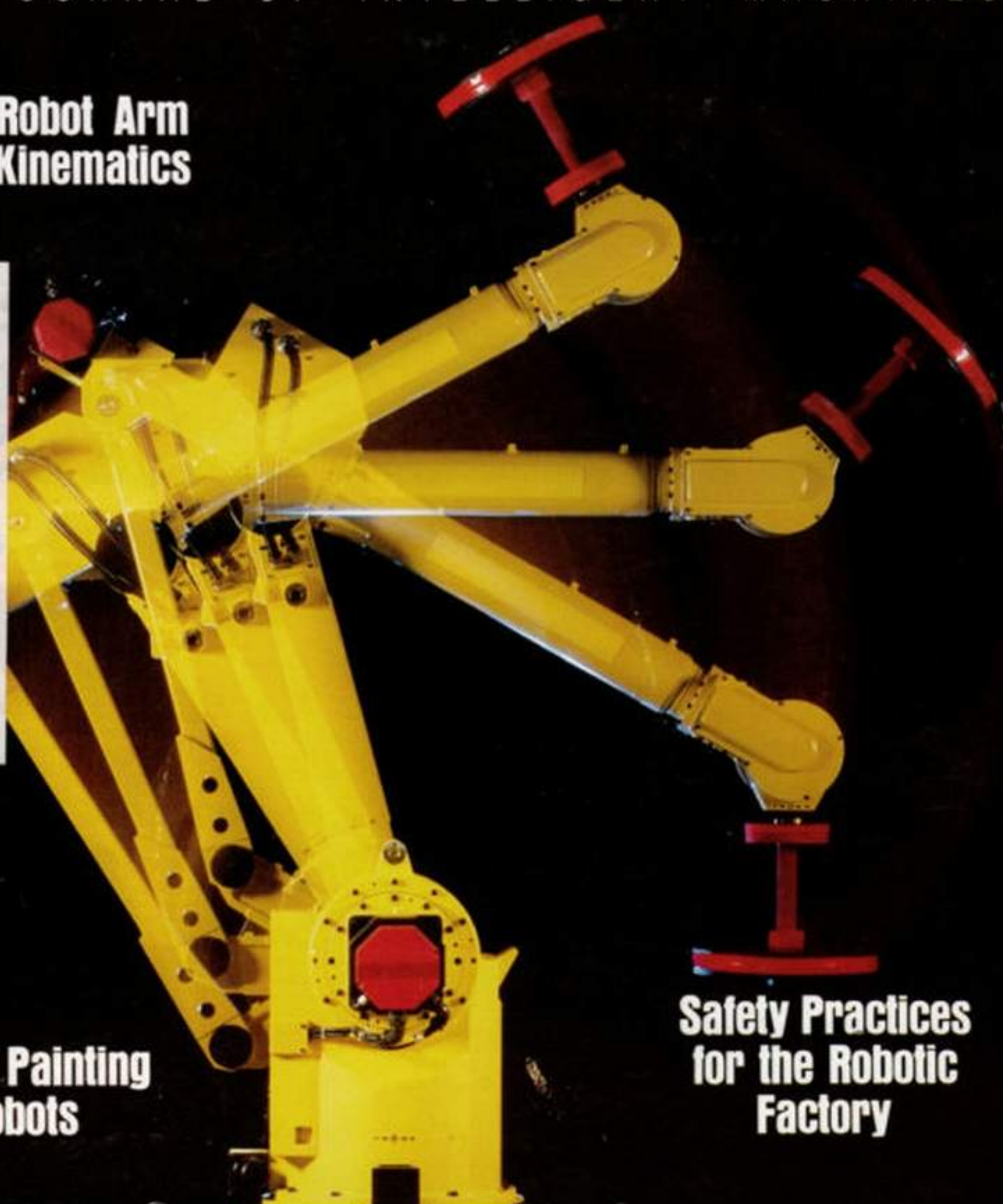
THE JOURNAL OF INTELLIGENT MACHINES

**Robot Arm
Kinematics**



**Spray Painting
Robots**

**Safety Practices
for the Robotic
Factory**



AUGUST 1986 VOL. 8 NO. 8

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES

**Simulation for
Robotic Workcell
Design and
Verification**

**Robots
in the
Laboratory**



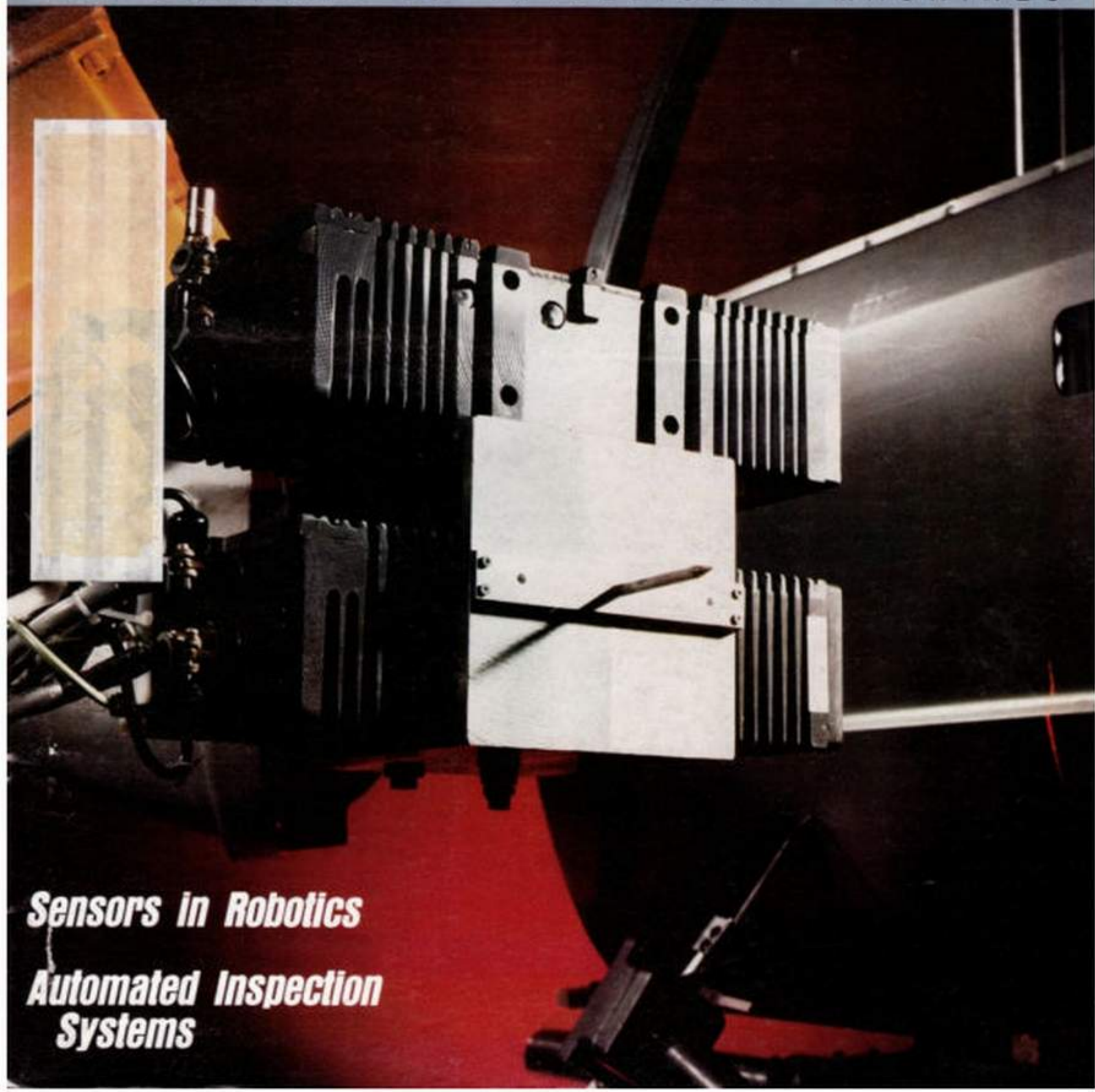
SEPTEMBER 1986 VOL. 8 NO. 9

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



Sensors in Robotics

***Automated Inspection
Systems***

OCTOBER 1986 VOL.8 NO.10

\$3.00 USA/\$3.50 CANADA

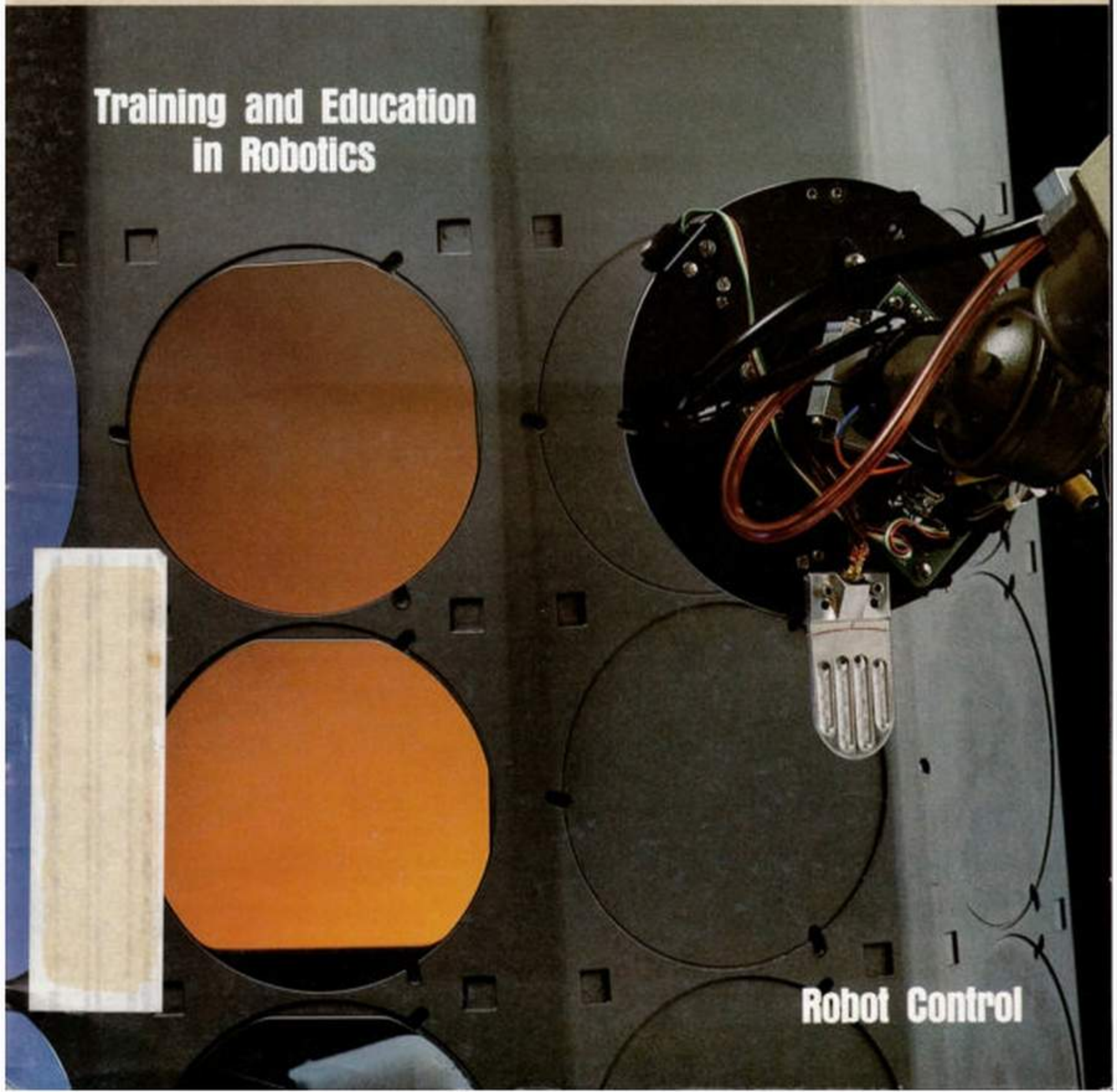
ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES

**Training and Education
in Robotics**

Robot Control



NOVEMBER 1986 VOL.8 NO.11

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES



**CIM and
Networking**

**Controlling a
Dual-Arm Robot**

DECEMBER 1986 VOL.8 NO.12

\$3.00 USA/\$3.50 CANADA

ROBOTICS

E N G I N E E R I N G

THE JOURNAL OF INTELLIGENT MACHINES

Mobile Robots

**Robot Justification
and Verification**



**Robots:
the future arrives...**



Scene: An asteroid mining team of the 21st century. Not a human team, but a team of self-replicating intelligent robots.

1961 Enter the first industrial robot—blind and unable to respond to its environment—capable only of unvarying, repetitive tasks.

1975 Robots with touch sensing begin to do precision assembly.

1981 Robots are no longer blind—silhouette vision arrives.

1982 Robots feel with an artificial skin.

1986 Robots adapt to the unstructured human environment.

1987 Reasoning robots hear and speak human speech.

1990 Walking robots explore the surface of Mars.

1996 Orbiting robot factories construct solar power stations.

2000 and beyond: Self-replicating robots terraform the cosmos.

This future is unfolding today exclusively in the pages of *Robotics Age*. Every two months we bring you the latest state-of-the-art robotic technology—from artificial intelligence, to automated robotic factories, to personal robots. Join us in the robotics age.



The advances that make this a picture of our future are happening today.

Robotics Age Magazine, Post Office Box 423, Tujunga, California 91042

ROBOTICS AGE BACK ISSUES

SUMMER 1979: Digital Speed Control of DC Motors; Industrial Robots '79; Introduction to Robot Vision; The Grivet Chess-Playing Arm. (photocopy)

WINTER 1979: Advances in Switched-Mode Power Conversion, Part I; Prospects for Robots in Space; Robotics Research in Japan; Report from IJCAI6.

SPRING 1980: Microcomputer Based Path Control; Robotics Research in France; Multiple Sensors for a Low-Cost Robot; the Robots of Autofact II; Inside Big Trak.

SUMMER 1980: Industrial Robots: Today and Tomorrow; Introducing the Minimover 5; Advances in Switched Mode Power, Part II.

FALL 1980: Using Optical Shaft Encoders; Interview with Victor Scheinman; Robot Vision for Industry; The Autovision System; Industrial Robotics '80; Robots on Your Own Time; Superkim Meets ET2.

MAR/APR 1981: Video Signal Input; Chain-Code; Camera Geometry for Robot Vision; TIG Welding with Robots; Robot Digestive Track—Robots on Your Own Time.

JULY/AUG 1981: Segmenting Binary Images; The Robot as Transfer Device; Continuous Path Control of Stepper Motors; TIMEL: A Homebuilt Robot.

SEPT/OCT 1981: Bullish Days in the Robot Business; Edge Detection in Man & Machine; Continuous Path Control with Stepping Motors; Build a Low-Cost Image Digitizer; Report from JACC-81; The Robot Builder's Bookshelf.

NOV/DEC 1981: Teach Your Robot to Speak; Fast Trig Functions for Robot Control; An Interview with George Devol; The Great Japanese Robot Show; TIMEL: A Homebuilt Robot, Part II.

JAN/FEB 1982: Avatar: A Homebuilt Robot; A Look at SS-50 Computer Boards; Working Within Limits; Ambulatron: Another Contest Winner; Quester.

MAR/APR 1982: The Rhino XR-1: A Hands-On Introduction to Robotics; Power for Robots; A Computer Controlled Sentry Robot; A Homebuilt Project Report; Natural Language Understanding; A First Look; RT-13 Video/Sound Recognition System; An Inexpensive Hand; Type N Talk.

MAY/JUNE 1982: Part Sources for Robots; An Inexpensive Arm-Hand System; The Polaroid P100 Polapulse Battery: Solution Waiting for a Problem; New Robot Books for the Bookcase; Applying Robot Vision to the Real World; Robots VI: A Landmark in an Exciting Era; Photo Essay and Notes from Robot VI.

JULY/AUG 1982: The Microbot Teach-mover; Some Notes On the Rhino XR-1 and Minimover 5; Patent Probe: Use Your Apple As a Robotics Development System; IBM Robots; Adapting a Speech Synthesizer; Constructing an Intelligent Mobile Platform, Part I.

SEPT/OCT 1982: Roving Robots; Report on SIGGRAPH '82; Patent Probe No. 4,221,997; Constructing an Intelligent Mobile Platform, Part II; The Physics of One-Legged Mobile Robots.

NOV/DEC 1982: Robot Wrist Actuators; Patent Probe: A Microcomputer Based, Real-Time Robot System; The Physics of One-Legged Mobile Robots; Part II; 1982 AAAI Conference; Armatron: A Study in Arm Engineering; Invention Documentation: A Primer.

JAN/FEB 1983: The Move-Master RM-101; Mailmobiles in the Office; Teaching the Rhino XR-1 to Write; The Philosophy and Birth of Computer Science; The 2-Roll Gripper.

MAR/APR 1983: Nuclear Power Plant Emergency Damage Control Robot; Artificial Intelligence and the Nature of Robotics; Patent Probe: Driverless Vehicle Autoguide; Lambertson Robots.

MAY/JUNE 1983: Patent Probe: Multi-Purpose Mechanical Hand; XY Interpolation Algorithms; Designing With Optical Shaft Encoders; A Table of Contemporary Manipulator Devices; An Algorithmic Approach to Intelligent Robot Mobility.

JULY/AUG 1983: The Get Away Special, Part I; A Nose for the Heath Hero-1; Patent Probe: Ambulatory Platform; Robotics and the Law: Organizing the Venture; A Table of Contemporary Manipulator Devices.

SEPT/OCT 1983: ODEX 1: The First Functionoid; A Cog-Wheel Driven Robot Cart; A Table of Contemporary Manipulator Devices; Patent Probe: A Portable Robot Task Analyzer; The Penpad: Handwritten Input for Computers; The Get Away Special, Part II: Flight Preparations.

NOV/DEC 1983: Complete Control with Forth on a Chip; A Simple Sense of Touch for Robotic Fingers; Current Offerings in Robotics Education; Single Board Computer Manufacturers; A Table of Contemporary Manipulator Devices; Welding Apparatus with Vision Correction.

JANUARY 1984: Robots in Batch Manufacturing; Super Armatron; Directory of Robotics Education and Training Institutions; A Table of Contemporary Manipulator Devices; Patent Probe: A New Robot Patent Category; Operator Roles in Robotics; The Scorpion: Software Overview.

FEBRUARY 1984: GRASP: From Computer Aided Robot Design to Off-Line Programming; Design and Construction of a Five-Fingered Robotic Hand; Patent Probe: Omnidirectional Vehicle; Using Microprocessors with Radio-Control Servos; Designing a Reliable Voice-Input Robot Control Language; Part II, The Scorpion: Motor Control Instructions.

MARCH 1984: Part I, Armega 33: Mechanical Design; Patent Probe: Robot Computer Chess; Part III, The Scorpion: Commands with Responses; A Simple Computer Interface.

APRIL 1984: Closing the Sensor-Computer-Control Loop; Bipedal Balance; Patent Probe: Robot Warehouse; Part II, Armega 33: The Electrical Components.

MAY 1984: Backyard Foundry for Sand Casting; Androtext, A High-Level Language for Personal Robots; Part III; Armega 33: Computer Control; Computers in the Real World.

JUNE 1984: Introduction to Numerical Control Programming; Glossary of CNC and Machine Tool Technology; A Glance at Some Microprocessor-Controlled CNC Tools; Intel's Bitbus Microcontroller Interconnect.

JULY 1984: Shape Memory Effect Alloys for Robotic Devices; Hitachi's Robot Hand; Part II, Backyard Foundry for Sand Casting; Making the Molds; Fantasy Meets Reality at New York Robot Exhibit; Meccano and the Home-Built Robot; The Role of Robots in Flexible Manufacturing Systems; A Review of the Colne Arm-droid I.

AUGUST 1984: Animate vs. Inanimate; The Echo II Speech Synthesizer; Computer Vision and Ranging Systems for a Ping Pong Playing Robot; Robots and Employment; Angles and Brads; Robots & Exposition and Conference; Part of the Beginning.

SEPTEMBER 1984: Tabletop Technology; Robots in the Classroom; Robots in Elementary Education; Moravec's Mobile Robots; Robotics' Role in HighTech Education; Using the Polaroid Ultrasonic Ranging System.

OCTOBER 1984: Introduction to Data Acquisition; A Simple Thermal Touch Sensor; Experimenting Made Easy; The ADC-1 Data Acquisition System; Of Mice and Machines.

NOVEMBER 1984: Part I, A Lisp-Based Robot Control System; Part I, Introduction to Prolog; EARL: An Easy Robot Language; Product Notes: The String Computer; A Biological Model for Multilegged Robot Control.

DECEMBER 1984: Motion Control for Automation and Robotics; A Lisp-Based Robot Control System, Part II; Robotix, Part I; Introduction to Prolog, Part II; A Third-Generation Stepper Motor Controller, Part I.

JANUARY 1985: The Walking Gyro; Nomad MK III: The Flight of Fancy; Robotix, Part II; External Control; A Lisp-Based Robot

Control System, Part III: An Example Environment; Rethinking Robot Mobility; A Pneumatic Walking Robot.

FEBRUARY 1985: The Sandi Project; Photo Essay: A First Glimpse at Gemini; Robotics Research: The Next Five Years and Beyond; Report from the Unmanned Vehicles Conference; A Modular Remote Data Acquisition System Design; Keeping the HERO I's Steering Wheel Straight; A Third-Generation Stepper Motor Controller: Part II.

MARCH 1985: Miniature CCD Cameras: A New Technology for Machine Vision; Vision and the Computer: An Overview; PC-Based Image Processing; Polaroid Ultrasonic Ranging Sensors in Robotics Applications.

APRIL 1985: Speech Recognition: Machines that Listen; Interview with Joseph Engelberger; The Listeners: Intelligent Machines with Voice Technology; Fourth for Computer Vision in Industrial Applications; A Second-Generation Autonomous Sentry Robot.

MAY 1985: The ABCs of X-Y Positioning; A Compliant Mechanical Gripper; Third-Generation Robots: Their Definition, Characteristics, and Applications; A Critique of Three Gripper Designs; Tool-Changing Robot Hands.

JUNE 1985: Justifying the Robotics Replacement Decision; A New Computerized Tomographic-Aided Robotic Stereotaxis System; A Z80-Based, Multitasking Control System; Recognizing Parts That Touch.

JULY 1985: A New Super Camera for Vision Systems; Force Sensors for Robotic Assembly Systems; A Multielement Ultrasonic Ranging Array; Goal-Seeking Sensor; Robots and Safety: An Industry Overview.

AUGUST 1985: The Exact Inverse Kinematics Solutions for the Rhino XR-2 Robot Manipulator; Previewing Robotic Motion with Computer Graphics; Inverse Robot Kinematics Derived from Planes of Movement; Graphics Simulation and Programming for Robotic Workcell Design.

SEPTEMBER 1985: FORTH for Robot Control; KAREL: A Programming Language for the Factory Floor; Robotalk: A New Language to Control the Rhino Robot; Robotics and Industrial Reeducation; Using LOGO for Robot Simulation.

OCTOBER 1985: Multiple-Arm Robot Control Systems; Programmable Logic Controllers Spearhead Factory Automation; An Intelligent Data Acquisition Controller; Assembly Robots With Overlapping Work Envelopes; Another Compliant Mechanical Gripper.

NOVEMBER 1985: Robotics in the Navy; Coordinated Motion in Robotics and Automation; Military Robotics: An Overview; Trends and Transitions in the Robotics Industry.

_____	Copies Summer '79 (photocopy)	Vol.1 No.1	\$15/ea.
_____	Copies Winter '79	Vol.1 No.2	\$3/ea.
_____	Copies Spring '80	Vol.2 No.1	\$3/ea.
_____	Copies Summer '80	Vol.2 No.2	\$3/ea.
_____	Copies Fall '80	Vol.2 No.3	\$3/ea.
_____	Copies Mar/Apr '81	Vol.3 No.2	\$3/ea.
_____	Copies July/Aug '81	Vol.3 No.4	\$3/ea.
_____	Copies Sept/Oct '81	Vol.3 No.5	\$3/ea.
_____	Copies Nov/Dec '81	Vol.3 No.6	\$3/ea.
_____	Copies Jan/Feb '82	Vol.4 No.1	\$3/ea.
_____	Copies Mar/Apr '82	Vol.4 No.2	\$3/ea.
_____	Copies May/June '82	Vol.4 No.3	\$3/ea.
_____	Copies Jul/Aug '82	Vol.4 No.4	\$3/ea.
_____	Copies Sept/Oct '82	Vol.4 No.5	\$3/ea.
_____	Copies Nov/Dec '82	Vol.4 No.6	\$3/ea.
_____	Copies Jan/Feb '83	Vol.5 No.1	\$3/ea.
_____	Copies Mar/Apr '83	Vol.5 No.2	\$3/ea.
_____	Copies May/June '83	Vol.5 No.3	\$3/ea.
_____	Copies July/Aug '83	Vol.5 No.4	\$3/ea.
_____	Copies Sept/Oct '83	Vol.5 No.5	\$3/ea.
_____	Copies Nov/Dec '83	Vol.5 No.6	\$3/ea.
_____	Copies January '84	Vol.6 No.1	\$3/ea.
_____	Copies February '84	Vol.6 No.2	\$3/ea.
_____	Copies March '84	Vol.6 No.3	\$3/ea.
_____	Copies April '84	Vol.6 No.4	\$3/ea.
_____	Copies May '84	Vol.6 No.5	\$3/ea.
_____	Copies June '84	Vol.6 No.6	\$3/ea.
_____	Copies July '84	Vol.6 No.7	\$3/ea.
_____	Copies August '84	Vol.6 No.8	\$3/ea.
_____	Copies September '84	Vol.6 No.9	\$3/ea.
_____	Copies October '84	Vol.6 No.10	\$3/ea.
_____	Copies November '84	Vol.6 No.11	\$3/ea.
_____	Copies December '84	Vol.6 No.12	\$3/ea.
_____	Copies January '85	Vol.7 No.1	\$3/ea.
_____	Copies February '85	Vol.7 No.2	\$3/ea.
_____	Copies March '85	Vol.7 No.3	\$3/ea.
_____	Copies April '85	Vol.7 No.4	\$3/ea.
_____	Copies May '85	Vol.7 No.5	\$3/ea.
_____	Copies June '85	Vol.7 No.6	\$3/ea.
_____	Copies July '85	Vol.7 No.7	\$3/ea.
_____	Copies August '85	Vol.7 No.8	\$3/ea.
_____	Copies September '85	Vol.7 No.9	\$3/ea.
_____	Copies October '85	Vol.7 No.10	\$3/ea.
_____	Copies November '85	Vol.7 No.11	\$3/ea.

12/85 RA-D

Send to:

ROBOTICS AGE
174 Concord St.
Peterborough, NH 03458



SPECIAL OFFER:

With my order of 10 or more back issues, please send me FREE, the photocopy of the Summer 1979 issue—a \$15.00 value!

Send in your name, address, and payment to receive any back issues of ROBOTICS AGE you've missed. Payment must accompany order—back issues cannot be billed.

For individual back issues add \$1.50 postage and handling for the first back issue. For each additional back issue add 50¢.

Cost of Back issues _____
Postage and Handling _____
Total Payment Enclosed _____

NAME _____

ADDRESS _____

CITY _____ STATE _____ ZIP _____